

AUTOMATIC SOLUTIONS

Australia Pty Ltd

ASA600 – ID200

Look for these. They
are "Tips N Tricks"



Solar information
and connections are
on the last page.

GENERAL

ASA600

Motor Voltage – 12 volt
Power Absorbed – 70 watts
Speed – 0,019 metres per second
Maximum Thrust – 1500 N
Protection Level – IP43
Duty Cycle – 90%
Dimensions – 970L x 90W x 185H
Stroke – 60 CM
Maximum Leaf – 5 metres
Maximum Leaf Weight – 250 Kg
Opening Time – 31 Seconds

ID200

Motor Voltage - 12 / 24 DC
Motor Inputs - Two
Battery Charger – Inbuilt 12/24V
Receiver – Inbuilt or External
Limit Switches – No
Pedestrian Input – Yes (NO)
Start Input - Yes (NO)
Stop Input – Yes (NC)
Photocell Input – Two (NC)
Electric Lock – Yes 12Vdc 1A
Slow Speed Regulator – Yes

IMPORTANT— READ THIS FIRST

Parts of these instructions are intended as a quick start guide and should be used in conjunction with the full instructions. The quick start instructions provide the basics to get you up and running and are based on the most commonly used installations in Australia. All electrical work in this country is to be performed by licensed electrical contractors. Electricity can kill!

SAFETY

This booklet will offer you information you may need to install your gear motor and to safeguard your safety.

However, caution is unquestionably indispensable and nothing is better than preventing accidents.

WARNING: any repair or adjustment of working machinery is strictly prohibited unless all the necessary precautions (electrical supply disconnected and motor off) have been taken in order to avoid possible accidents.

WARNING: any repair must be carried out by qualified people.

WARNING: All moving mechanisms must be provided with suitable protections.

WARNING: Keep the automatic controls out of the reach of children.

WARNING: Command pulses must be given from positions where the gate is visible.

WARNING: Use transmitters only if you can see the gate.

Read carefully the instructions enclosed in this manual.

Keep this booklet in a suitable place well known to all interested people.

PRELIMINARY CHECKS

In order to make the automation work efficiently; the gate to automate must have the following characteristics:

- It must be balanced.
- It must oscillate fluently.
- You must be able to carry out manual closing and opening of the gate without any effort.
- Make sure that the gate has a solid structure and that there is no friction points in its movement.
- Make sure that the gate/s have both solid opening stops and solid closing stops.

GENERAL ORDER OF INSTALLATION

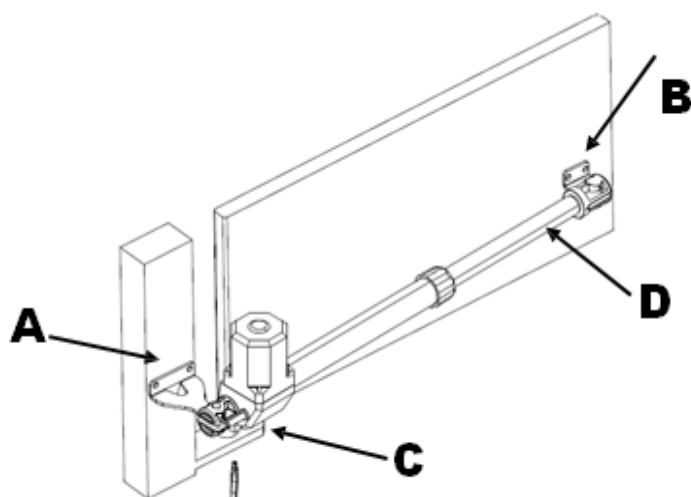
To ensure a good installation of the gear motors ASA600, we suggest the following order of installation:

- 1 - Open the box and take out gear motor. Inspect the contents and ensure all components are present.
- 2 - Make sure that the leaf of the gate is perfectly horizontal.
- 3 - Determine the height position of your motor and mark post bracket position.
- 4 - Spend some time here considering the correct height and geometry of your post bracket.
- 5 - Attach the gear motor on to the support post.
- 6 - With gate/s leaf closed, turn and slide the screw of gear motor's shaft, until it comes to the end of the screw.
- 7 - Screw shaft back 1 complete turn of 360°.
- 8 - Place the gate support plate in the hole of the shaft end and position it against the gate leaf.
- 9 - Fix it to the gate leaf taking in account the inclination.
- 10 - Put the gear motor into manual operation mode with your override key and test your install for smoothness.
- 11 - If correct proceed in the same way with the other gate leaf.
- 12 - Place the mechanical limit stops
- 13 - Connect the gear motors to the logic controller.
- 14 - Program and test your installation
- 15 - Attach your safety devices and access devices one by one testing for correct operation at each point.

MAINTENANCE

Periodically check your installation for loose or worn fastenings, correct alignment and operation of your gate/s and correct operation of your manual override operation. Clean and keep clean all areas of the installation. Remember that the motorisation has been planned in order to help you use the gate. This means that it does not resolve the problems caused by an inadequate installation or by a poor upkeep of the gate.

ASA600 GEAR MOTOR INSTALLATION

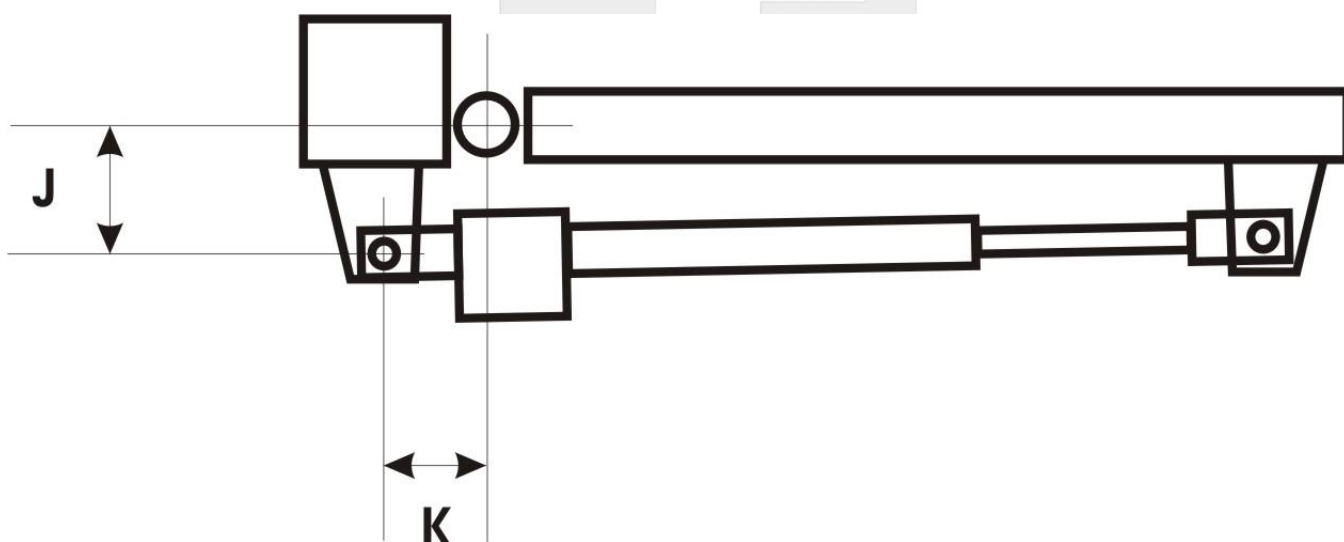


INSTALL POST BRACKET

The position of the post bracket "A" is critical to the success of your installation and attention needs to be paid to both its correct height and also its position on the post in respect to the relationship between your gate hinge pivot point and the motor pivot point on the bracket.

Once you have determined the general desired height of your motor, position the bracket and take note of dimensions "J" and "K". In a standard installation the basic aim is to get dimensions "J" and "K" to be as close as possible to equal.

The other consideration before fixing the post bracket is that the pivot point of the post bracket "A" should be 12mm higher than the pivot point of the gate bracket "B" giving the gear motor an incline of approximately one degree.



INSTALL GATE BRACKET

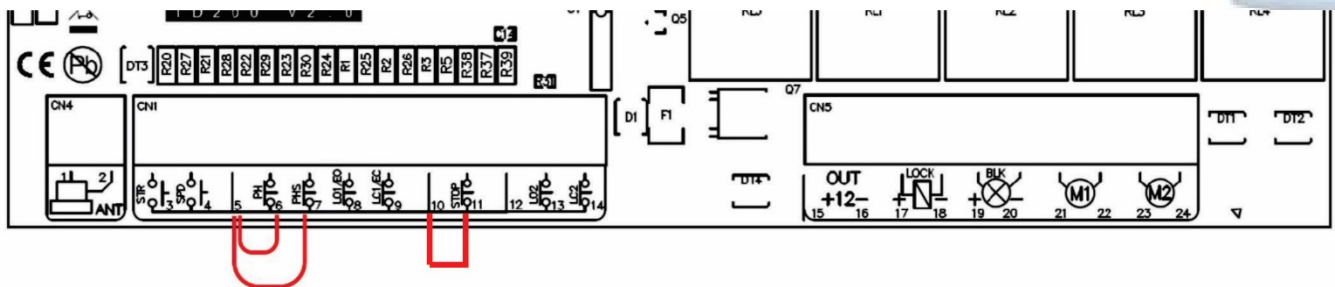
With your post bracket securely fastened, attach your gear motor to the post bracket with the bolts provided. Take care to support the weight of the gear motor at this point and throughout this stage. Wind out shaft "D" all the way till the end. Now turn shaft "D" back one complete turn of 360 degrees. Attach your gate bracket to the shaft end "H" and position on the gate taking careful note of your 12mm fall from the post bracket. Fix your gate bracket at this position. Using your manual override key put the gear motor into manual mode and gently move your gate and gear motor through the entire 90 degree arc to test the smoothness of your installation. If your gate and gear motor moves smoothly through the entire travel range then you are ready to proceed to the next point. If you are having difficulty or hitting sticking points at any point in the travel you may need to adjust your post bracket pivot point to facilitate a smoother run.

INSTALL GATE STOPS

This is a critical point in ensuring long trouble free operation of your automation system, yet it is relatively simple. Each gate must have a positive and well secured opening stop and closing stop. There are a range of stops available over the counter or you can make them yourself but the critical point is that the stops must be well secured as the gear motors will exert quite a deal of force on them during programming. In summary when your gate/s open they must hit a positive stop point that stop the gate/s from opening any further and the same at the closed point.

TIPS & TRICKS

ID200 V2



- **TIP** – Always install the motor/s and program using safety loops as described below before installing accessories. Accessories should be installed one by one following successfully installing and programming the motors.
- **TIP** – You need to fit three small loops of wire to your safety inputs to make anything work. These need to be removed later if you install safety devices to these input terminals. But for now, take two pieces of light gauge wire (speaker or telephone wire is good) about 40mm long and strip both ends 7mm and insert them as above from 5 to 6, and 5 to 7. Also 10 to 11.
 - **TIP** - Ensure JP1 on the control board is set to the correct voltage for your system.
- **TIP** – The transformer has two voltages. Use red and black for 12 volts or red and green for 24 volts. These connect to FS3 and FS4.
 - **TIP** – If using one motor only (single gate) use the terminals for Motor 2.
- **TIP** – The manual offers simple setup. It works well. Manual programming gives more control and is used by professional installers to adjust settings. You can also.
- **TIP** – If using solar power refer to the manual for correct input power connection (Last two pages). Also get hold of a copy of the solar power tips n tricks.
- **TIP** – If using wireless keypad KEYPADP6 set it to 20Bit mode to work with this board.

CONVERTING FROM AN OLD K50 OR CTR50

- The terminals from J1 (left side) are now terminals 15 to 24 (right side)
 - The terminals from J2 (middle) are now terminals 3 to 14 (left side)
 - If you are using one motor only still use motor 2. Terminals 23 and 24.
- Your power input and battery connect to the same terminals as the old K50 or CTR50.
- As your installation used the K50 / CTR50 board your mechanical stops should all be in place so you might find it easiest to program using the “AU” method (automatic). You can make adjustments via the menu from there. Just be certain to start with the gates in the fully open position.

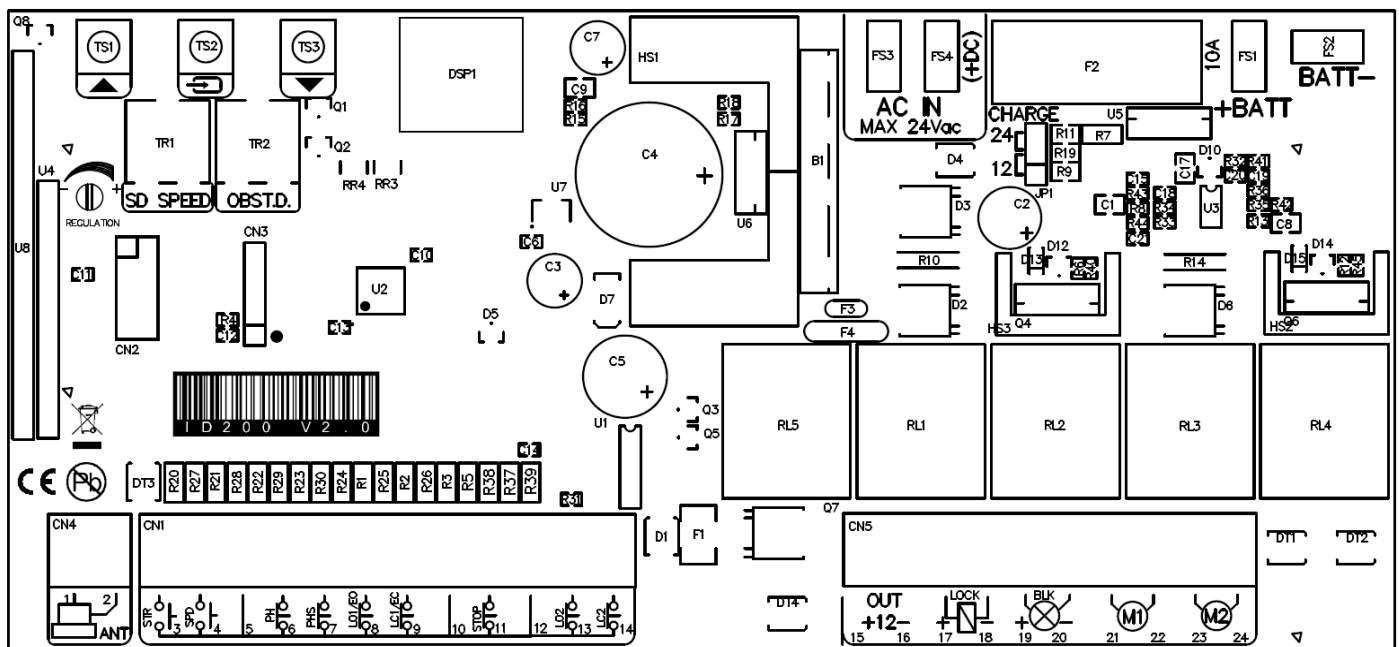
Control unit low voltage

For 2 motors

ID200 V2

GB Instructions Manual

Rev. 2,0



Important: Read carefully this manual before the installation. This manual is integral part of your product, keep it for reference.

Warnings: First of all verify that this product is suitable for the installation. Read carefully technical characteristic before the installation.

Installation of this control unit must be properly done by qualified installers, following rules and regulations of installation country.

It's mandatory do periodic maintenance each 6 month. Maintenance or repairing must be done by qualified Technicians. Turn power off before maintenance or repairing.

This device is intended for gate automation, any other applications is strongly advised.

Not respecting of rules may cause serious damage to peoples, animals, things. Manufacturer discharges all responsibility for missed respect of rules.

Don't let this control unit unattended or where children can reach

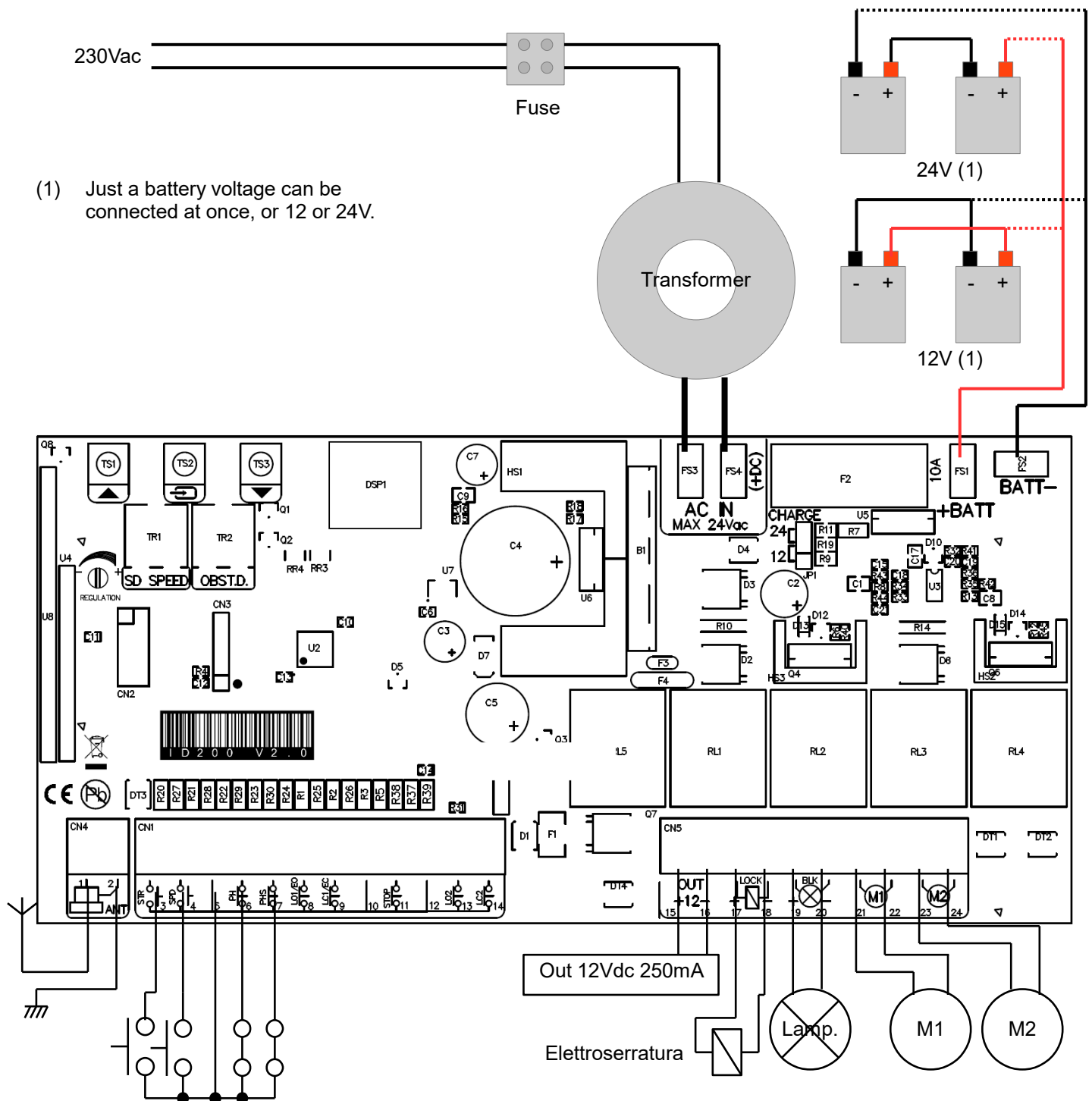
Preliminary checking: Before to install this control unit, verify that all the connected devices respect the technical characteristics mentioned in the table which follows. Verify that a working and suitable life switch is installed upline the installation. Verify that cables composing the installation, are suitable for it.

Technical characteristics

Power Supply	12-20Vac/100-200VA
Max. Current out	250mA
Embedded Battery charger	12/24V 100mA
Max motor current	8A (200VA transformer)
Max flashing light current	1A
Max electriclock current	2A
Operating temperature range	-5 +60°C
Backup battery	(2x) 12V 4.5Ah

Wiring

Main functions



- 1 Antenna.
- 2 Antenna's shield.
- 3 Start input N.O. or Open input N.O. (See menu operative logic "□L").
- 4 Start Pedestrian input N.O. or Open input N.O. (See menu operative logic "□L").
- 5 Common
- 6 Photocells input N.C. or N.O (see advanced menu "P□").

7	Photostop input N.C. or Detect input N.O. (see advanced menu "SF").
8	Opening Edge or Limit Switch open for slave motor 1 (see advanced menu "E□").
9	Closing Edge or Limit Switch close for slave motor 1 (see advanced menu "E□").
10	Common.
11	Stop input N.C. or N.O. (see advanced menu "SP").
12	Common.
13	Limit Switch open for master motor 2. Left unconnected both limit switches 2 they are automatically disabled.
14	Limit Switch close for master motor 2. Left unconnected both limit switches 2 they are automatically disabled.
15-16	Aux power supply output 12Vdc 250mA.
17-18	Electric lock output (12/24Vdc, according to transformer output).
19-20	Flashing light output (12/24Vdc, 1A, according to transformer output). With blinking or fix output. A very slow blinking it alerts for power failure.
21-22	Output slave motor 1 (12/24Vdc, according to transformer output).
23-24	Output master motor 2 (12/24Vdc, according to transformer output).
TR1	Slow down speed trimmer.
TR2	Obstacle detection sensitivity trimmer.
TS1	Up button.
TS2	Enter button.
TS3	Down button.
DSP	Display
FS3- FS4	Transformer input 12-20Vac / 100-200VA
F2	Rapid fuse 10A.
FS1- FS2	Backup battery in 12/24Vdc (attention: select right value)
JP1	Charger voltage selector for backup battery: 12/24Vdc

Inputs status

When the control unit is in standby, user can read inputs status on display:

- : No inputs active.
- SP : Stop input active.
- PS : Photostop input active.
- E□ : Analog edge opening input active.
- E□ : Analog edge closing input active.
- P□ : Photocells input active.
- SE : Start input active.
- Pd : Pedestrian input active.
- P : Open input active.
- L : □lose input active.
- : Limit switch open motor 1 (slave) active.
- : Limit switch close motor 1 (slave) active.
- : Limit switch open motor 2 (master) active.
- : Limit switch close motor 2 (master) active.

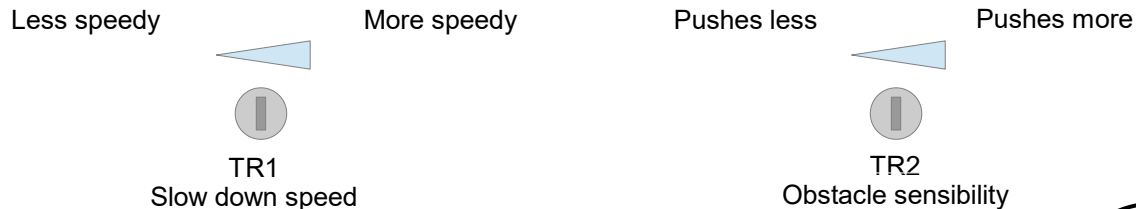
During pause, the display show the seconds countdown to closing.

Trimmers setting

Slow down speed trimmer regulates the slow down speed. Do not set speed too low (less than 10cm/sec on the wing edge) to avoid that gate stops in very cold conditions.

Obstacle sensibility trimmer fine tunes the obstacle detection level learned by the control unit during working times programming. This fine regulation must be do after working times learning.

Normally the trimmer goes in the center, in this position it should suit most installations. If it is necessary to resolve problems related to norms or to environmental situations (ex. strong wind) is it possible to regulate this trimmer increasing or decreasing sensibility.



Simple Setup



1. Check motor direction

Push and release the ENTER button. The display will show $\square L$. Use UP/DOWN buttons to select $\square \uparrow$. Press ENTER and now select available options (Open motor 1, Close motor 1 etc.) and hold the ENTER button down to check your motor direction. Example - If you only have one motor it should be connected to M2. Use the option $\square 2$ to check that motor is opening. If not stop - reverse the two motor wires in M2 and test again. When happy with motor/s direction you can exit this menu and again to exit all menus.

To exit this menu select EH or push up and down together.

After 20 seconds without actions, control unit exits itself from this menu.

2. Choose single or double gate mode.

The control board by default is set to double gate so this next step is only for single gate installations. To enter advanced menu hold down the ENTER button for 4 seconds, until the display shows $\square \uparrow$. Use the UP/DOWN buttons to select $\square \square$. Use the UP/DOWN buttons to find $\square 5$ and press ENTER to select for single gate mode.

To exit this menu select EH or push up and down together.

After 20 seconds without actions, control unit exits itself from this menu.

3. Quick program.

To program the working times, open the gate/s, then keep pushed UP till you read $\square \square$ on the display. The control unit will do several tests and then it will learn working times. When the procedure is finished the LED screen returns to normal.

4. Quick radio code learning.

Push the DOWN button, " $\square \downarrow$ " will appear on display. Transmit with the remote to be learnt as Start or Open command (according to " $\square L$ " menu). Push twice DOWN to select pedestrian start

5. Quick radio code erasing:

Hold down DOWN button up to on display it appears " $\square \downarrow$ " (5 seconds about), then release the button. All codes are now erased.

6. Auto learning transmitters.

It's possible to learn transmitters quickly without using the base menu. To insert a new transmitter transmit 3 times with the new remote, making at least 1 second pause between each transmission. Then transmit 3 times with a transmitter already in memory and then once with the new. When programming is done, the blinker flash once. **Attention:** function must be enabled, refer to "advanced menu" - auto learning transmitters. The new code takes the same channel as the one used to insert it.

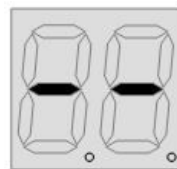
Board Programming

Main menu

Push Enter button shortly, on the display will appear **OL**. With up/down it's possible to select all items in this menu.

To exit this menu select **EH** or push *up* and *down* together.

After 20 seconds without actions, control unit exits itself from this menu.



Push
shortly
Enter

Display	Function	Choiches	Description	Default
OL	Operative logic	St At cd oc oA EH	Step By Step. Step by step with automatic closing. Condominium mode. Open / Close mode (Start and Pedestrian inputs become Open and Close inputs). Open / Close mode with automatic closing (Start and Pedestrian inputs become Open and Close inputs). Exit.	St
Lc	Learning/ removing transmitters	cl c2 rt rn rA EH	Learn Start / Open command (according to OL menu). Learn Pedestrian / Close command (according to OL menu). Removing a remote transmitting its own code. Removing a remote according memory position. Removing all the remotes, must confirm with " YS " Exit.	-
Lt	Learn working time	 At nn	<p>Attention, before to start learning working times the gate must be set completely open for automatic procedure, while completely closed for manual mode learning. You could use dead man mode "dn" to do it. Is it possible to use a shortcut to start automatic working time procedure, see quick programming chapter.</p> <p>Automatic working times learning (Set the gate fully open before to start the procedure). Attention: in all the procedure safety devices are disabled. The gate pushes in opening direction for a while, than it start closing. In this phases the obstacle detection levels and working times are detected. If you are using a single motor, please set the single motor mode by using "Sc" menu, and connect the motor on output 2 (master).</p> <p>Manual working times learning (set gate fully closed before to start this procedure). Attention: it's need to learn at least a remote in memory before to start the procedure. in all the procedure safety devices are disabled. The gate starts opening, in this phase you can set the slowing down speed by the related trimmer. When the gate is fully open, push enter button or transmit with a remote. In this phase the obstacle detection values are detected, when the test is done nn appears on the display. In the next steps, the enter button or a memorised remote act as it follows: slave motor 1 starting closing, master motor 2 start closing, slow down motor 1 starts, slow down motor 2 starts, stop motor 1, stop motor 2. If you are installing a single gate motor, set the times just for 1 motor.</p>	-
SP	Automatic closing pause time	0- 99	Set the automatic closing pause time in seconds.	10

Main menu (Continue)

Display	Function	Choiches	Description	Default
d1	Dearman mode	o1 c1 o2 c2 EH	Open motor 1. Close motor 1. Open motor 2. Close motor 2. Exit.	-
EH	Exit	-	Exit from main menu.	-

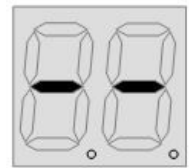
Board programming

Advanced menu

To enter advanced menu hold down enter button 4 seconds, till on display it appear **e1**. With up/down it's possible to select all items in this menu.

To exit this menu select **EH** or push *up* and *down* together.

After 20 seconds without actions, control unit exits itself from this menu.



Push
Enter
4 seconds

Display	Function	Choiches	Description	Default
e1	Time menu	e1 s1 e2 s2 do dc eL EH	Working time slave motor 1 (in seconds). Slowing down start time (since start) of slave motor 1. Working time master motor 2 (in seconds). Slowing down start time (since start) of master motor 2. Delay time of slave motor in opening direction (in seconds). Delay time of master motor 2 in closing direction (in seconds). Electric lock on time. If set to 0 the lock output works as Open gate light (ON when gate is open). Exit.	25 22 25 22 02 05 02
55	Single motor mode	45 nE	Single motor gate Double wing gate	nE
d2	Resets to defaults	45 nE EH	Confirming with 45 the control unit is reset to factory defaults. Attention, this procedure doesn't erase the radio codes.	-
rC	Release motor pressure.	45 nE	The gate reverses for few tenths once he has reach the end. Normal operations.	nE
Ar	Automatic remotes learning	45 nE	Automatic remotes learning enabled. Automatic remotes learning disabled.	nE
c5	Kickback stroke	45 nE	Kickback stroke enabled. Kickback stroke disabled.	nE
55	Soft start	45 nE	Soft start enabled. Soft start disabled.	45
5L	Limit switches in series to the motor	45 nE	Limit switches in series to the motor (opening the circuit) Normal operations.	nE

Advanced menu (Continue)

Display	Function	Choiches	Description	Default
ร 0	Radio mode	1b 4b	Each radio button is learned separate. The installed can choose ho to learn a code: (c 1 Start/Open, c 2 Pedestrian/close). Learning a button of a remote, let all the other 3 buttons being learn automatically.	1b
L 0	Electric Lock mode	45 0b	Magnetic electric lock. Impulsive electric lock.	0b
E 0	Opening Edge mode	d5 00 0c A0 L5 EH	Disabled. Normally Open. Normally Close. Analogic input 8K2. Limit switch open slave motor 1 Exit.	d5
E c	Closing Edge mode	d5 00 0c A0 L5 EH	Disabled. Normally Open. Normally Close. Analogic input 8K2. Limit switch close slave motor 1 Exit.	d5
P c	Photocell mode	0c 00	Normally Open. Normally Close. Attention: Rules of several countries forbit to use safety systems with N.O. Output. Please be sure of safety regulations of your country before to modify this parameter.	0c
SP	Stop mode	0c 00	Normally Open. Normally Close. Attention: Rules of several countries forbit to use safety systems with N.O. Output. Please be sure of safety regulations of your country before to modify this parameter.	0c
SF	Safety input mode	P5 dE	Photostop mode N.C. (Photocell operating in opening mode too) Detect mode N.O.(Photocell for rapid close after the car has passe through the gate)	dE
L5	Limit switches mode (all 4 LS)	0c 00	Normally Close. Normally Open.	0c
bL	Blinker mode	45 0b	Flashing output. Fix on output.	45
c 0	Cycles counter	-	Shows cycle counter in 3 group of 2 digits. Example: 123.456 is shown as: 12 - 34 - 56	-
EH	Exit	-	Exits advanced menu.	-

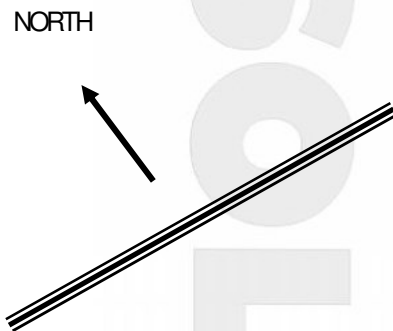
GENERAL SOLAR NOTES

SOLAR PANEL SIZE

Generally speaking simple automatic gate installations will work perfectly in Australia using a 10 watt solar panel. The solar panel size determines the amount of energy you can collect each day. In a simple gate installation we need to collect enough energy to power our control board and run the gate and a 10 watt panel will do this. If however the installation is to include keypads, safety beams or other power hungry devices it may be necessary to increase the solar panel size. Another example where you may wish to consider upsizing your solar panel is where you may have a partially shaded area and you need to collect your energy each day in a shorter period of time. If you do decide to increase the size of your solar panel it may be necessary to install a simple regulator to protect your battery. Check with Automatic Solutions regarding this.

SOLAR PANEL DIRECTION

Your solar panel ideally should be mounted at an angle of 35 degrees and facing north (NB: In Australia).

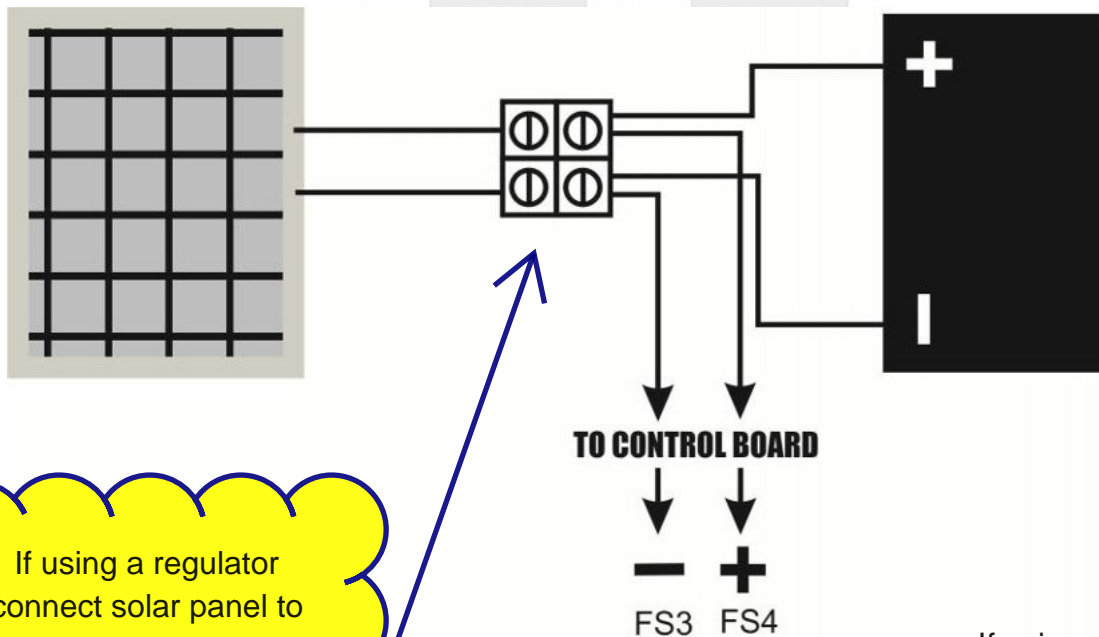


BATTERY SIZE

The battery stores the energy that you collect each day and your system draws on this battery to operate. All batteries have a limit to their storage capacity and can therefore only store enough energy to last our system a certain period of time. What happens if we have for example three days with little or no sunlight, very dark and overcast days? Our battery capacity reduces. The size of the battery will determine the number of days we can have as backup or how many days our system can survive without charging. In general terms bigger is better.

CABLES

Cables must be low voltage cables (5mm is good). Length of cables must be kept to a minimum. Ideally the solar panel will be no more than 10 metres from the battery and the battery will be no more than 5 metres from the motor. Connections must be clean and good quality.



If using a regulator connect solar panel to regulator, regulator to battery and then battery to control board. Do not take the board to the regulator.

If using a regulator go solar panel to regulator, regulator to battery and then battery to control board. Do not take the board to the regulator.

Solar Panel Connection ID200

