



**ASA6000240V**

**BOOM GATE**

**INSTALLATION MANUAL**



## IMPORTANT

Your new electro mechanical boom gate is manufactured in compliance with high levels of quality and reliability; this will guarantee performance and safety over time.

Enclosed in this booklet, you will find all the information necessary for assembling your gear motor and ensuring your safety.

-  **This instruction booklet is designed for professional installers** who are familiar with the manufacturing criteria and the safety and protection devices available to prevent accidents for gates, doors and power operated gates (respect standards and laws in force).
-  The installer must provide suitable instruction and issue the final user with an instruction booklet in accordance with EN 12635.
-  Before proceeding with installation, the installer must analyse the risks of final automated closing and ensure that the whole system is in safe condition (in compliance with the EN 12453 and EN 12445 standards).
-  The various electrical components which make up the automated closing system (e.g. photocells, flashing lights etc.) must be wired in compliance with EN 60204-1 and the modifications to this in point 5.2.2 of EN 12453.
-  Any operation to repair or adjust the equipment is forbidden unless all due precautions in order to prevent possible accidents have been taken (e.g. electrical power disconnected, motor blocked). All moving components must be equipped with suitable protection devices.
-  The power line must be protected for the maximum current when the rotor is blocked.
-  All repair operations must be performed by qualified personnel.
-  Keep the automation controls out of the reach of children. All switches must be installed at a minimum height of 1.5 m from the ground and out of the radius of action of moving parts.
-  Only activate the remote control when the boom gate is visible. All command operations must only be carried out at points where the boom gate is completely visible.
-  Any arbitrary modification to this product releases Automatic Solutions Australia Pty Ltd from all responsibility resulting from damage or injury to objects, persons or animals.
-  Disregarding the safety standards listed herein and the regulations in force releases Automatic Solutions Australia Pty Ltd from all responsibility resulting from damage or injury to objects, persons or animals.
-  Keep this manual safely in a suitable place known to all persons involved.
-  The automation must be coupled with a control unit equipped with torque adjustment which provides an intrinsic crush-prevention safety device as referred to in the EN 12453 – EN 12445 standards.

## USING THE BOOM GATE - GENERAL DESCRIPTION

The ASA6000240V boom gate is suitable for managing passageways with average levels of transit and comply with the UNI 12 453 standard.

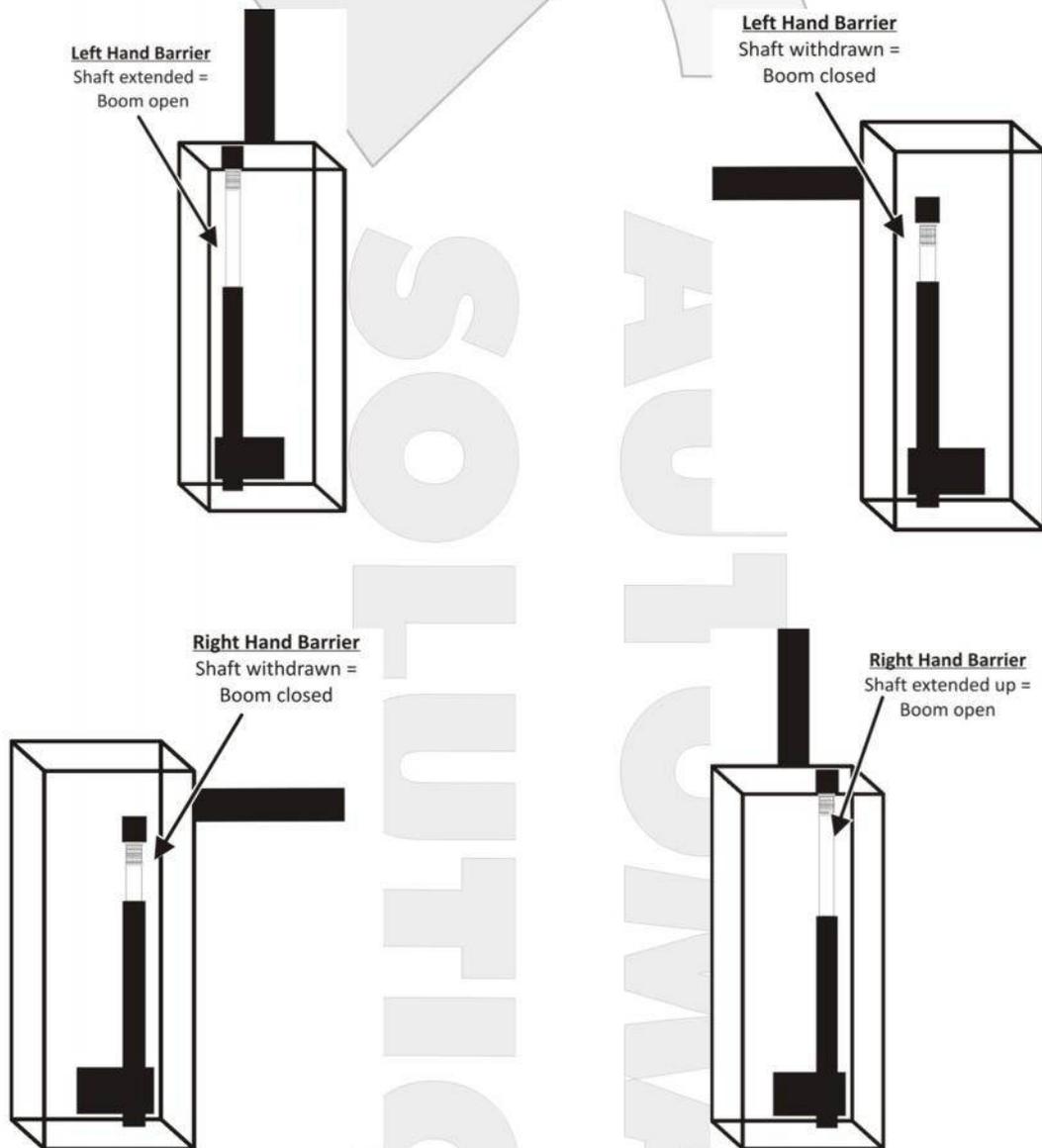
- The movement of the boom is regular with gradual decelerations at the opening and closing positions. The barrier is identified by the CE marking plate.
- Adjusting the run between the two mechanical end runs and balancing the barrier by preloading the movement return spring is easy by moving the nut / counter-nut sets.
- In the event of a power cut, a simple key unlocking system allows the boom gate to be unlocked with the consequent intervention of the return spring which moves the barrier to the vertical position without any external help.
- The crush-prevention safety device is ensured by the preloading of the spring which opposes the action of the boom gate which, where suitably calibrated, ensures that a force is available for movement which guarantees that the barrier stops upon minimal contact with an obstacle.
- The load-bearing casing is made of galvanised steel and is powder-coated.
- Movement is ensured by an asynchronous motor in order to guarantee high levels of reliability over time.

TECHNICAL DATA	ASA6000240V
POWER SUPPLY (V 240AC 50/60Hz)	240
INPUT POWER (W)	350
INPUT CURRENT(A)	1.0
CAPACITATOR ( F)	12.5
OPENING TIME (sec)	9.5
CLOSING TIME (sec)	9.5
MAX. BAR LENGTH (m)	6.0mtr / 7.5kg
MOTOR SPEED	1400
OPERATING TEMPERATURE (°C)	-25 +60
THERMAL PROTECTION (°C)	150
PROTECTION RATING (IP)	40
WORKING CYCLE (%) / DAILY MANOEUVRES	40 / > 2000
MOVEMENT	ELECTROMECHANICAL PISTON
UN LOCKING	MANUAL - WITH KEY
DIMENSIONS AND WEIGHT	324x282x1130mm / 44.5 kg

## SUGGESTED ORDER OF INSTALLATION

1. Unpack all package contents and ensure all parts are correct and available.
2. Examine site conditions to determine left or right installation and suitability for base installation.
3. Install base plate if required.
4. Modify left – right configuration of the boom gate if necessary.
5. Securely fasten the boom gate to the prepared base.
6. Attach the boom.
7. Install boom support if used.
8. Adjust boom tension as required.
9. Adjust open and close stops.
10. Apply power to the control board.
11. Program the board and test the operation.
12. Make adjustments as necessary.
13. Attach safety and ingress and egress devices one at a time testing after each addition.

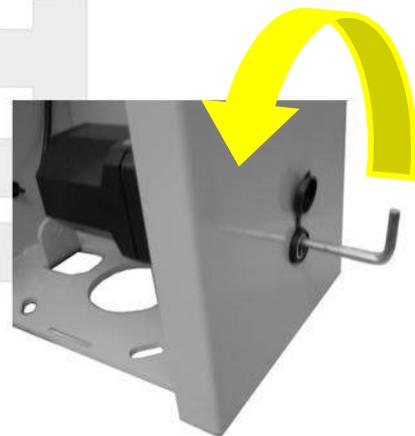
## DETERMINING LEFT AND RIGHT INSTALLATIONS



### MANUAL OPENING

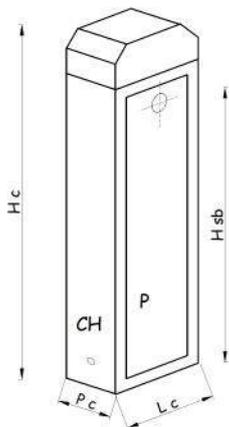
In the event of a power cut or in any other situation which makes it necessary to open the moveable barrier without electrical power, proceed as follows:

- Insert the key supplied in the base of the column in the designated circular hole;
- Turn the key anti-clockwise to unlock the automation-barrier connection (clockwise direction to lock the automation-barrier connection) and use one hand to help the barrier up. The action of the preload spring will help the operation.



## OVERALL DIMENSIONS AND POSITIONING

- The barrier movement mechanism is easily adaptable to provide right-hand or left-hand closing (as seen from the barrier side). See instructions for changing the opening side.
- For safe use, it is necessary to provide suitable space for the automation access panel opening (P) and to be able to activate the unblocking key (CH) for the emergency manoeuvre.
- Securing to the ground takes place by anchoring a base plate equipped with suitable anchor bolts or embedded in a purpose prepared concrete pad.

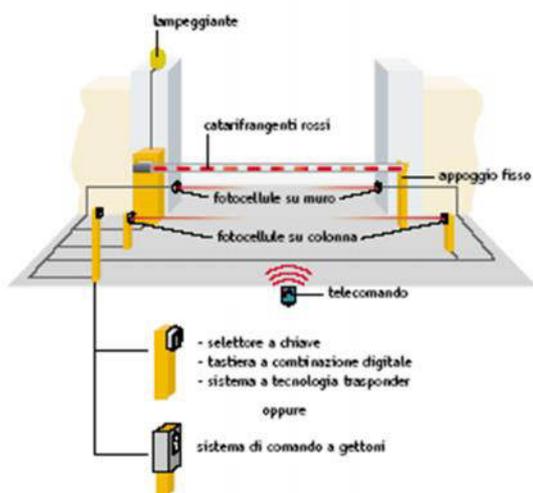


BASE PLATE

Model	Max length L	Hsb	H c	Wid. c	Depth c
ASA6000	6000	900	1225	325	225

## SUGGESTED SAFE OPERATING CONDITIONS:

- Affix an adhesive band with reflective strips onto the barrier arm, to highlight it;
- Install a fixed support at the end of the barrier;
- Install a system of photocells, as shown in the figure, to prevent the automatic re-closing system from intervening during the transit of persons or vehicles;
- Check that, in the open and closed positions, the barrier is easily visible both during the day and at night. Add suitable additional lighting where necessary;
- Install a flashing light to activate during barrier movement (optional)



## **MODIFYING THE BARRIER CLOSING DIRECTION (RIGHT/LEFT)**

The barrier is supplied with the closing as requested (right/left) (as seen from the barrier side).

If the direction of access is to be inverted, the barrier is fully reversible and with simple operations, it is possible to reverse it, following the instructions below.

- Disconnect power to the barrier; lock the switch with the key and open the hatch (P) and the head cover (C).
- With the boom removed whilst in the upright (open) position lighten the load on the balancing spring and remove.
- Remove the fasteners from the ends of the motor (threaded lock pin and pin) and remove.
- Reposition the pivoting rocker arm of the automatism to the other side and refit the motor on the opposite side first securing it at the base and then at the top, inserting the pin in the eyelet, and then reload the spring on the other side and pretension.
- Install the boom in the open vertical position and adjust the spring so that in manual mode the boom supports itself at 45 degrees – that is that it neither drops suddenly nor rises by itself.

# ***CITY1 CONTROL BOARD***

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## IMPORTANT REMARKS

**GR Sistemi automatici di aperture Srl has the right to modify the product without previous notice; it also declines any responsibility to damage or injury to people or things caused by improper use or wrong installation.**

**\_Please read this instruction manual very carefully before installing and programming your control unit.**



This instruction manual is only for qualified technicians, who specialize in installations and automations.



The contents of this instruction manual do not concern the end user.



Every programming and/or every maintenance service should be done only by qualified technicians.

**AUTOMATION MUST BE IMPLEMENTED IN COMPLIANCE WITH THE EUROPEAN REGULATIONS IN FORCE:**

**EN 60204-1** (Machinery safety. electrical equipment of machines, part 1: general rules)

**EN 12445** (Safe use of automated locking devices, test methods)

**EN 12453** (Safe use of automated locking devices, requirements)



The installer must provide for a device (es. Magnetotermical switch) ensuring the omnipolar sectioning of the equipment from the power supply. The standards require a separation of the contacts of at least 3 mm in each pole (EN 60335-1).



After making connections on the terminal board, use one hose clamp to fix dangerous voltage wires near the terminal board and another hose clamp to fix safety low voltage wires used for accessories connection; this way, in case of accidental detachment of a conducting wire, dangerous voltage parts will not come into contact with safety low voltage ones.



The plastic case has an IP55 insulation; to connect flexible or rigid pipes, use pipe fittings having the same insulation level.



Installation requires mechanical and electrical skills, therefore it shall be carried out by qualified personnel only, who can issue the Compliance Certificate concerning the whole installation (Machine Directive 2006/42/CEE, Annex IIA).



The automated vehicular gates shall comply with the following rules: EN 13241-1, EN 12453, EN 12445 as well as any local rule in force.



Also the automation upstream electric system shall comply with the laws and rules in force and be carried out workmanlike.



The door thrust force adjustment shall be measured by means of a proper tool and adjusted according to the max. limits, which EN 12453 allows.



We recommend to make use of an emergency button, to be installed by the automation (connected to the control unit STOP input) so that the gate may be immediately stopped in case of danger.

## DECLARATION OF CONFORMITY

The producer hereby declare that CITY1 products conform to the essential requirements established in the following directives:

- 2004/108/CEE (EMC Directive in accordance with standards EN 55014-1, EN 55014-2, EN 61000-3-2, 61000-3-3)

- 2006/95/CEE (Low Voltage Directive in accordance with standards EN 60335-1 + EN 60335-2-103)

- 99/05/CEE (Radio Directive in accordance with standard EN 301 489-3)

## TECHNICAL SPECIFICATIONS

<b>CITY1</b>	<b>220V</b>	<b>120V</b>
Power supply	230Vac – 50Hz	120VAC – 60Hz
Max motors load	2x700W	2x500W
Duty cycle	40%	30%
Max accessories load 24V	10W	10W
Working temp.	-20 – +60°C	-20 – +60°C
Protection fuse	F1 = 5A	F1 = 8A
Dimensions	295x230x100mm	
Weight	1600g	
Protection	IP55	

## DESCRIPTION OF THE CONTROL UNIT

The digital control unit **CITY1** is an innovative product that guarantees a safe and reliable automation of leaf swing or sliding gates.

**CITY1** is provided with a display that, not only makes programming simple, but also allows a continuous monitoring of the input statuses; in addition, thanks to a menu structure, the working schedule and the operation logic can be set easily.

In compliance with the European standards concerning electrical safety and electromagnetic compatibility (EN 60335-1, EN 50081-1 and EN 50082-1) it has been equipped with the low voltage circuit total electric insulation (motors included) from the network voltage.

Other characteristics:

- Automatic control for the null current relay switch.
- Power adjustment with independent wave shutting on both the two motors.
- Obstacle detection by means of monitoring start condenser voltage.
- Automatic learning of the operation time.
- Operation by means of mechanical ends of stroke connected to the gearcase or connected in series to the motor.
- Tests for safety devices (photocells, safety ribbons and triacs) before each opening.
- Deactivation of safety inputs through the configuration menu: no jumper is required for terminals concerning safety devices that have not been installed, yet. You will only need to disable this function from its relevant menu.
- Control unit programming can be locked through the optional **CL1** key.

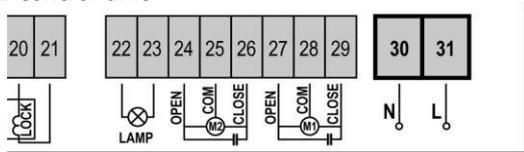
## INSTALLATION

Installation of control unit and safety devices must be carried out with power disconnected.

## POWER SUPPLY

The control unit must be fed by a 230V 50Hz (120V - 50/60Hz for the model CITY1-120V) electric line, protected by a differential magnetothermal switch complying with the law provisions in force.

Connect power supply cables to terminals **30** and **31** of CITY1 control unit



## MOTORS

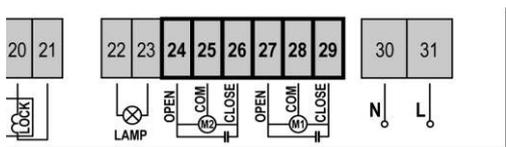
**CITY1** control unit can control one or two alternate current asynchronous motors. If the control unit needs to control one motor only, the latter must be connected to terminals of motor 1.

Connect motor 1 cables as follows:

- opening cable to terminal **27**
- closing cable to terminal **29**
- common return cable to terminal **28**

Connect motor 2 (if any) cables as follows:

- opening cable to terminal **24**
- closing cable to terminal **26**
- common return cable to terminal **25**



## CONTROL OF THE CORRECT ORDER OF CLOSING LEAVES

If the leaves of the gate overlap during the closing phase, it is necessary to connect the motor of the leaves that must start first at the motor 1 terminals, and to arrange the delays (parameters r.AP and r.Ch) so that collision is avoided.

If the control unit detects a wrong overlap order (leaf 1 gets to the closing position before leaf 2), the gate is opened a little again so that it can close correctly.

If the leaves do not overlap (e.g. in a double swing gate) set to zero the opening door delay parameter in order to disable the control of the right closing order.

## WARNING (USING HYDRAULIC MOTORS):

- If using hydraulic motors, the following function could not work properly: Soft start, Slowing down and Obstacle sensor. In this case, such functions should be disabled from menu.
- Read carefully the working times self-learning procedure, described in the paragraph "QUICK CONFIGURATION", paying particular attention to the points where the procedure to be followed in case of disabled obstacle sensor is described



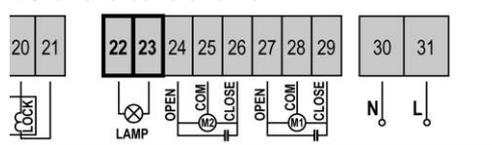
In case it has not yet fitted, a start capacitor for each motor is required; connect the start capacitor for motor 1 between terminals **27** and **29** and start capacitor for motor 2 (if any) between terminals **24** and **26**. • In case motor 2 is not connected, set menu **tAP2** to zero.



In case it has not yet fitted, a start capacitor for each motor is required; connect the start capacitor for motor 1 between terminals **27** and **29** and start capacitor for motor 2 (if any) between terminals **24** and **26**. • In case motor 2 is not connected, set menu **tAP2** to zero.

## BLINKER

**CITY1** control unit provides for a 230V 40W (120V - 40W for model **CITY1-120V**) blinker equipped with intermittence inside. Connect blinker cables to terminals **22** and **23** of the control unit



## PHOTOCELLS

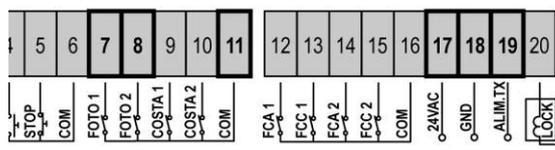
The control unit considers two kinds of photocells, depending on the terminal to which they are connected:

• **Photocell 1:** that is to say, photocells installed on the gate inner side, which are active both during the opening and the closing phase. When photocells 1 operate, the control unit stops the doors; as soon as the photocell beam is free, the control unit will open the gate completely.

• **Photocell 2:** that is to say, photocells installed on the external gate side and which are active during the closing phase only. When photocells 2 operate, the control unit opens the gate immediately, without waiting for release.

**CITY1** control unit supplies a 24VAC power supply to photocells and it can perform a photocell operation test before starting the gate opening phase. Photocell power terminals are protected by an electronic fuse that stops current in case of overload.

- Connect power supply cables of photocells transmitter between terminals **19** and **18** of the control unit.
- Connect power supply cables of photocells receiver between terminals **17** and **18** of the control unit.
- Connect receiver output of photocells 1 between terminals **7** and **11** of the control unit and receiver output of photocells 2 between terminals **8** and **11** of the control unit. Use outputs having normally closed contact.
- If several couples of same kind photocells are mounted, their outputs must be connected in series.
- In case of reflection photocells, power supply must be connected to terminals **19** and **18** of the control unit to carry out the operation test.



## SAFETY RIBBONS

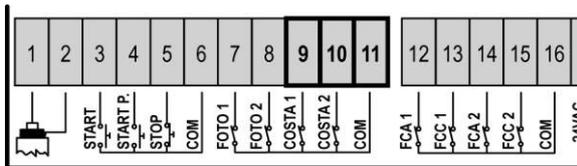
The control unit considers two kinds of safety ribbons, depending on the terminal to which they are connected:

- **Type 1 (fixed):** they are mounted on walls or on other fixed obstacles that are approached by the gate doors during the opening phase. When type 1 safety ribbons operate during the gate opening phase, the control unit will close the doors for 3 seconds, then it stands still; when type 1 safety ribbons operate during the gate closing phase, the control unit will stand still immediately. The direction of the gate at next command of START or PEDESTRIAN START depends upon the parameter STOP (it inverts or continues the motion). If the input STOP is disabled, the command makes the motion continue in the same direction.

- **Type 2 (mobile):** they are mounted to the door ends. When type 2 safety ribbons operate during the gate opening phase, the control unit will stand still immediately; when type 2 safety ribbons operate during the gate closing, the control unit will open the doors for 3 seconds, then it will stand still. The direction of the gate at next command of START or PEDESTRIAN START depends upon the parameter STOP (it inverts or continues the motion). If the input STOP is disabled, the command makes the motion continue in the same direction.

Connect type 1 safety ribbons cables between terminals **9** and **11** of the control unit.

Connect type 2 safety ribbons cables between terminals **10** and **11** of the control unit.



In order to meet the requirements of the EN12978 rules, it is necessary to install safety edges controlled by a control unit continuously checking the proper working. If using control units suited to the test by power outage, connect the power supply cables of the control unit between terminals 19 and 18 of the CITY1. Otherwise, connect them between terminals 17 and 18.



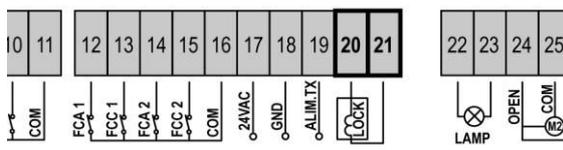
### WARNING:

- Make use of safety ribbons having outputs with normally close contact.
- Outputs of same kind safety ribbons must be connected in series

## LOCK

An electric lock can be assembled on the gate, to ensure a good closing of doors. Make use of a 12V lock.

Connect lock cables to terminals **20** and **21** of the control unit.

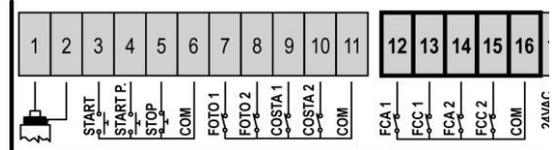


## END OF STROKE

**CITY1** control unit supports the two following kinds of end of stroke:

- end of stroke in series of motor winding.
- end of stroke equipped with a normally close switch that will be opened as soon as the door reaches its position desired. The control unit automatically recognizes ends of stroke in-series of the motor windings so no connection or programming is required. Ends of strokes equipped with a normally close switch must be connected to the control unit terminal board as follows:

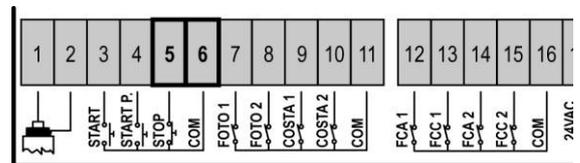
- opening end of stroke in door 1 between terminal **12** and **16**.
- closing end of stroke in door 1 between terminal **13** and **16**.
- opening end of stroke in door 2 between terminal **14** and **16**.
- closing end of stroke in door 2 between terminal **15** and **16**.



## STOP

For a better safety, you can fit a stop switch that will cause the immediate gate stop when activated. This switch must have a normally close contact that will get open in case of operation. In case the stop switch is operated while the gate is open, the automatic closing function will always be disabled. To close the gate again, you will need a start command (if the start function in pause is disabled, it will be temporarily enabled to allow the gate release).

Connect the stop switch cables between terminal **5** and **6** of the control unit.



The stop switch function can be activated by means of a remote control stored on channel 3 (see relevant instructions of MR1 receiver). The command STOP from remote is operative also if the input STOP of the terminal board is disabled.

**ACTIVATION INPUTS**

**CITY1** control unit is equipped with two activation inputs, whose operation depends on the programmed operation modes (see **Strt** item of programming menu):

- **Standard mode:** a command being on the first input will cause the complete opening of both leaves (start); a command being on the second input will cause the partial opening of leaf 1 only (pedestrian start).

- **Open/Close command and manned operation:** a command on the first input always controls the gate opening, while a command on the second input always controls the gate closing.

In Open/Close mode, there is an impulse command, that is to say that an impulse will cause the complete gate opening or closing.

In manned operation, there is a monostable command, that is to say, the gate will be opened or closed as long as the contact is closed and it will immediately stop as the contact is open.

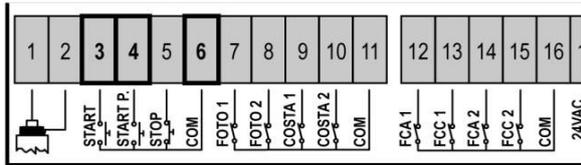
- **Timer mode:** it is similar to the standard mode but the gate stays open (completely or partially) while the contact is closed on input; as soon as the contact is open the pause

time count-down will start, after which the gate will be closed again. This function allows programming the gate opening time during the day, by making use of an external timer. Automatic closing must be enabled.

In all modes, inputs must be connected to devices having normally open contacts.

Connect cables of device controlling the first input between terminals **3** and **6** of the control unit.

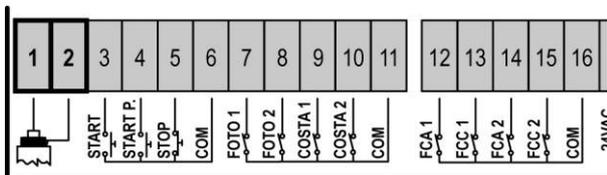
Connect cables of device controlling the second input between terminals **4** and **6** of the control unit.



The first input function can also be activated by pressing UP key outside the programming menu or by means of a remote control stored on channel 1 (see relevant instructions of MR1 receiver). The second input function can also be activated by pressing DOWN key outside the programming menu or by means of a remote control stored on channel 2.

**EXTERNAL AERIAL**

We suggest to use the external aerial (model ANSGP433) in order to guarantee the maximal range. Connect the antenna hot pole to terminal **1** of the control unit and the braiding to terminal **2**.



**PLUG IN RECEIVER**

**CITY1** control unit is suitable for plugging in a Personal Pass MR1 receiver having a high-sensitivity super-heterodyne architecture.

**WARNING: it is necessary to turn off the control unit power before doing the operations mentioned here below. Pay attention to the way you connect the removable modules.**

MR1 module receiver is provided with 4 channels and each of them is suitable for a command of **CITY1** control unit:

- CHANNEL 1 → START
- CHANNEL 2 → PEDESTRIAN START
- CHANNEL 3 → STOP
- CHANNEL 4 → OPTIONAL MODULS OUTPUT

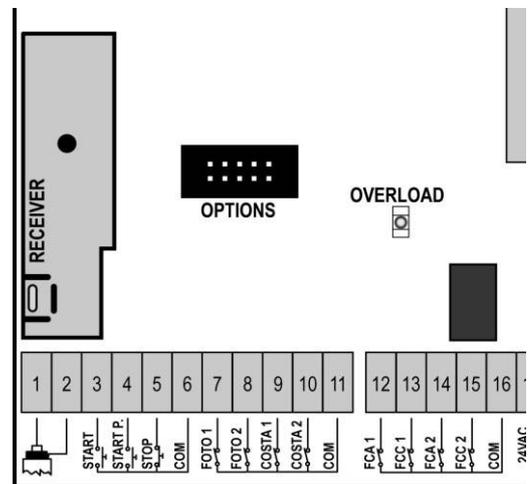
**WARNING: Before programming 4 channels and function logics read carefully the instructions of MR1**

**OPTIONAL MODULES**

The **CITY1** digital control unit, besides its excellent versatility, provides for the final user with the possibility to add new functions by means of optional modules. Its dedicated connector has been placed over the word **OPTIONS**.

**WARNING: Please read the instructions of each single module to install the optional modules.**

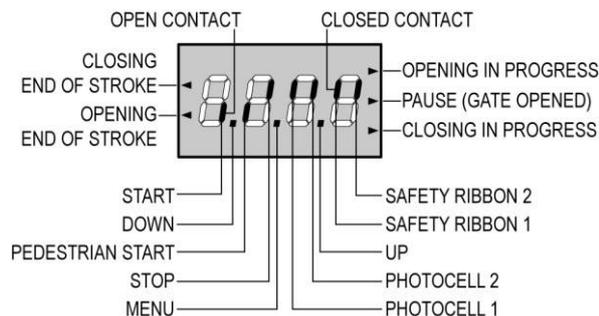
Connector for optional modules can also be used to plug in the programming lock key (cod. **CL1**), which prevents from any operation set-up change by non-authorized personnel.



## CONTROL PANEL

When power is on, the control unit checks that display correctly operates by switching on all segments for 1.5 sec. **8.8.8.8.**

Firmware version, e.g. **Pr 2.2**, will be viewed in the following 1.5 sec. Panel will be viewed upon completion of this test.



The control panel represents the physical status of the terminal board contacts and of the program mode keys: if the upper vertical segment is on, the contact is closed; if the lower vertical segment is on, the contact is open (the above picture shows an instance where the inputs START, START P, FOTO 1, FOTO 2, COSTA 1, COSTA 2 and STOP have all been correctly connected). Points being among display digits show the status of programming push-buttons: as soon as a push-button is pressed, its relevant point turns on.

The arrows on the display left side show the status of the ends of stroke. As for a one door-gate, arrows turn on when its end of stroke shows that the gate is completely closed or completely open.

As for a two-door gate, arrows turn on when both the ends of stroke show that both the doors are completely closed or completely open; the arrow will blink in case only one door reaches its end of stroke.



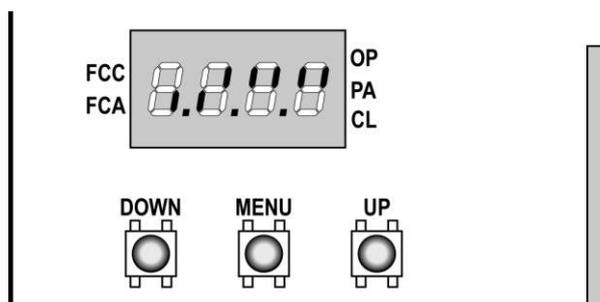
**WARNING: these functions have not been activated in case of ends of stroke being connected in series to the motor.**

The arrows on the display right side show the gate status:

- The highest arrow turns on when the gate is into its opening phase. If it blinks, it means that the opening has been caused by a safety device (border or obstacle detector).
- The central arrow shows that the gate is on pause. If it blinks, it means that the time countdown for the automatic closing has been activated.
- The lowest arrow blinks when the gate is into its closing phase. If it blinks, it means that the closing has been caused by a safety device (border or obstacle detector).

## USE OF DOWN MENU AND UP KEYS FOR PROGRAMMING

Control unit time and function programming is made within a special configuration menu, to which you can access and where you can shift through **DOWN**, **MENU** and **UP** keys placed under the display



Hold down the MENU key until **def** appears on display, to activate the programming mode while display views the panel.

Configuration menu consists of a list of configurable items; the wording appearing on display will show the current selected item.

By pressing DOWN, you will pass to the next item; by pressing UP, you will return to the previous item.

By pressing MENU, you can view the current value of selected item and possibly change it.

The last menu item (**FinE**) allows storing the carried out changes and going back to the control unit normal operation. You must exit from programming mode through this menu item if you do not want to lose your configuration.



**WARNING: in case no operation is carried out for more than one minute, the control unit exits from the programming mode without saving any of your setups and changes, which will get lost.**

By holding down the DOWN key, configuration menu items will scroll fast, until item **FinE** is viewed. Viceversa, by holding down the UP key, items will scroll fast backwards until item **def** is viewed. In this way, you can quickly reach either the top or bottom of the list. There are the following three kinds of menu items:

- Function menu
- Time menu
- Value menu

### Function menu setup

Function menus allow selecting a function from among a group of available options. When you enter into a function menu, the current active option will be viewed; you can scroll all available options through DOWN and UP keys. By pressing the MENU key, you will activate the option viewed and you will return to the configuration menu.

### Time menu setup

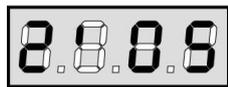
Time menus allow setting a function duration. When you enter into a time menu, the current setup value will be viewed; the display mode depends on the current value:

- times being lower than one minute will be viewed as follows:



each time you press UP key, current time value increases of half a second; vice versa, each time you press the DOWN key, current time value decreases of half a second.

- Times between 1 and 10 minutes will be viewed as follows:



each time you press UP key, current time value increases of 5 seconds; vice versa, each time you press the DOWN key, current time value decreases of 5 seconds.

- Times being more than 10 minutes will be viewed as follows:



each time you press UP key, current time value increases of half a minute; vice versa, each time you press the DOWN key, current time value decreases of half a minute.

By holding down the UP key, you can quickly increase the time value, up to reach the max. value allowed for this item. Vice versa, by holding down the DOWN key, you can quickly decrease the time value down to reach **0.0**".

In some circumstances, setting the value to 0 means that the relevant function is disabled, in this case, 'no' will appear instead of **0.0**".

By pressing on MENU you will confirm the displayed value and you will return to the configuration menu.

### Value menu setup

Value menus are similar to time menus; however, the setup value can be any number. By holding down UP or DOWN keys, the value will increase or decrease slowly.

### QUICK CONFIGURATION

This paragraph concerns a quick procedure to set the control unit and set it at work immediately. We recommend following these instructions, in order to check quickly the correct operation of control unit, motor and accessories, and then changing the configuration in case of any non-satisfactory parameter. Please refer to the paragraph "Control unit configuration" for the item position inside the menu, as well as for the available options for each item.

1. Call up a default configuration (item **def.**). Select **AntE** for a door-gate, select **Scor** for other configurations (sliding, rolling, sectional, etc.).
2. If you have a door gate with only one motor, set **t.AP2** opening time to zero.
3. In case there is no electric lock on the gate, set **t.SEr**, **t.ASE** and **t.CvE** values to zero.
4. Set items **StoP**, **Fot1**, **Fot2**, **CoS1**, **CoS2** e **FC.En** according to the safety devices installed on the gate.
5. Start the self-learning cycle (item **APPr**). This last operation will close the configuration menu and store set up parameters.

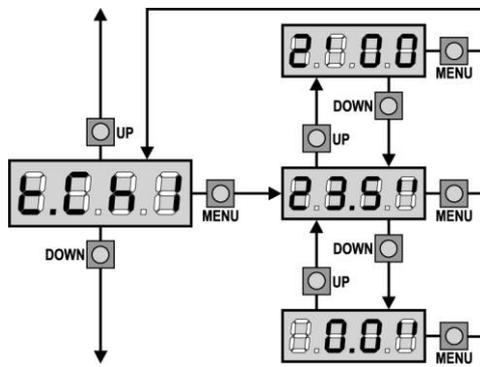
### Self-learning procedure if there are two motors:

- In case the ends of stroke, the encoder or the obstacle sensor have been enabled, the doors will be activated in closing direction until the stop end or the closing end of stroke is reached. Be sure that the leaves do not overlap.
- In case NEITHER the ends of stroke NOR the obstacle sensor have been enabled, be sure that the doors are completely closed when the procedure starts.
- The doors will be activated in opening direction until the stop end or the opening end of stroke is reached.
- In case the sensors have not been enabled, or if you realize that they do not signal the position to the control unit, you must send a first START command when leaf 1 reaches its max. opening position and then a second START command when leaf 2 completes its opening phase.
- The doors will be activated in closing direction until the stop end or the closing end of stroke is reached
- In case the sensors have not been enabled, or if you realize that they do not signal the position to the control unit, you must send a first START command when leaf 1 reaches its fully closed position and then a second START command when leaf 2 completes its closing phase.

### Self-learning procedure if there is one motor:

- In case the end of stroke, the encoder or the obstacle sensor has been enabled, the door will be activated in closing direction until the stop end or the closing end of stroke is reached.
- In case NEITHER the ends of stroke OR the obstacle sensor have been enabled, be sure that the door is completely closed when the procedure is started up.
- The door will be activated in opening direction until the stop end or the opening end of stroke is reached.
- In case the sensors have not been enabled, or if you realize that they do not signal the position to the control unit, you must send a START command when the door reaches its max. opening position.
- The door will be activated in closing direction until the stop end or the closing end of stroke is reached.
- In case the sensors have not been enabled, or if you realize that they do not signal the position to the control unit, you must send a START command must be sent when the door reaches its fully closed position.



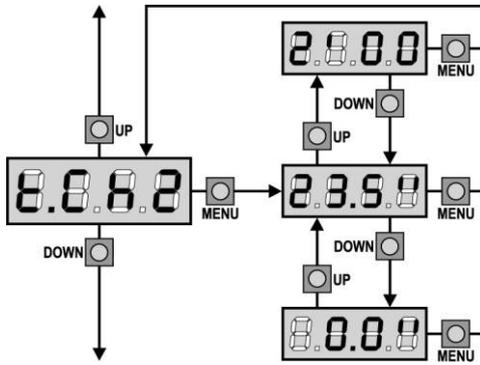


### Leaf 1 closing time

Motor 1 will be operated for the setup time in the closing phase;

In case there is an obstacle or the end of stroke operates, the control unit can stop the opening phase before the relevant time expires.

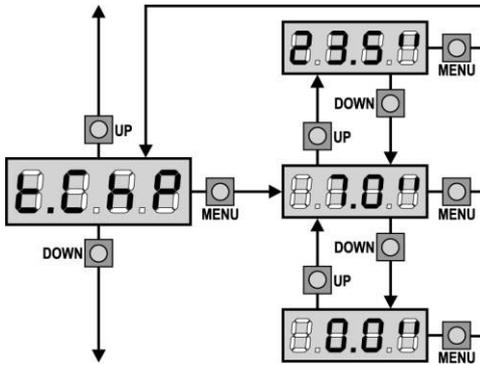
To avoid that the door does not close completely, we recommend to setup a longer time than **t.AP1** opening time.



### Leaf 2 closing time

Motor 2 will be operated for the setup time in the closing phase; the control unit can stop the opening phase before the relevant time expires, in case there is an obstacle or the end of stroke operates.

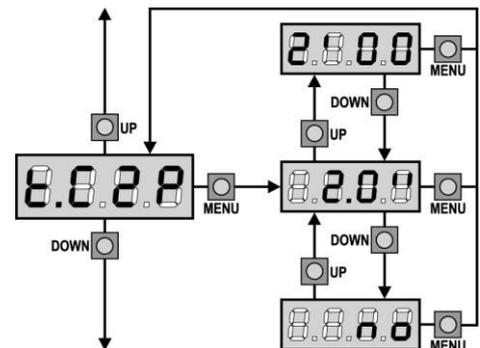
To avoid that the door does not close completely, we recommend to setup a longer time than **t.AP2** opening time.



### Partial closing time (pedestrian access)

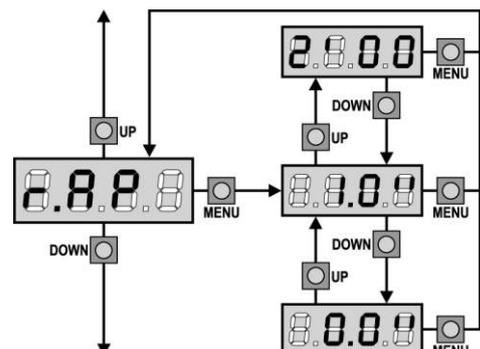
When the control unit receives a Start Pedestrian command, it will use this time to close the gate. Max allowed time to be setup is **t.CH1**.

To avoid that the door does not close completely, we recommend to setup a longer time than **t.APP** opening time.



### Leaf 2 closing time during pedestrian cycle

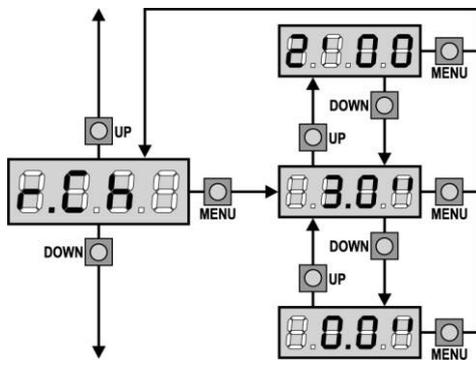
During a partial opening cycle (pedestrian access) leaf 2 may move slightly because of the wind or its own weight; in this case at closing time leaf 1 could hit leaf 2 and the gate would remain not perfectly closed. To avoid this, in the last seconds of the cycle a light closing force is applied to leaf 2 too. If the set time is greater than the time required to close leaf 1, leaf2 is driven at reduced power all the closing time long.



### Opening door delay

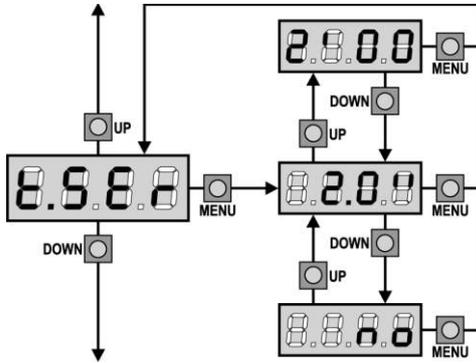
During the opening phase, leaf 1 must start moving before leaf 2, to avoid that both doors may collide. Leaf 2 opening will be delayed for the setup time.

If you set the opening door delay to zero, the control board does not execute the control of the correct leaves closing order.



### Closing door delay

During the closing phase, leaf 1 must start moving after leaf 2, to avoid that both doors may collide. Door 1 closing will be delayed for the setup time.

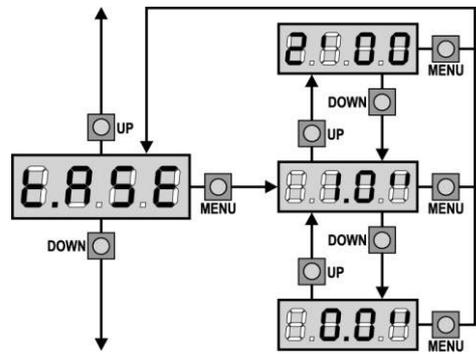


### Lock time

Before the opening phase begins, the control unit will energize the electric lock in order to release it and enable the gate motion.

**t.SEr** time will fix the energizing time.

**!** **WARNING:** in case the gate has no electric lock, set the value 0 ('no' will appear on display).

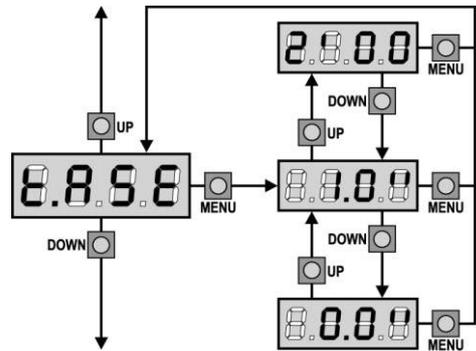


### Lock advance time

While the electric lock is energized, the gate will stay standstill for **t.ASE** time, to make its release easier.

In case **t.ASE** is lower than **t.SEr**, the lock energizing will go on while the doors will start moving.

**!** **WARNING:** in case the gate has no electric lock, set the value 0

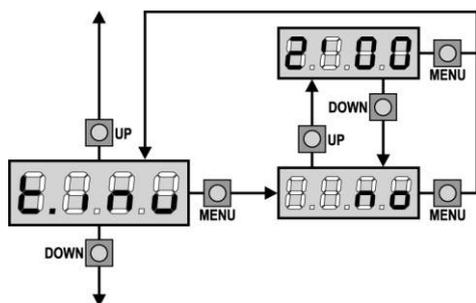


### Lock advance time

While the electric lock is energized, the gate will stay standstill for **t.ASE** time, to make its release easier.

In case **t.ASE** is lower than **t.SEr**, the lock energizing will go on while the doors will start moving.

**!** **WARNING:** in case the gate has no electric lock, set the value 0



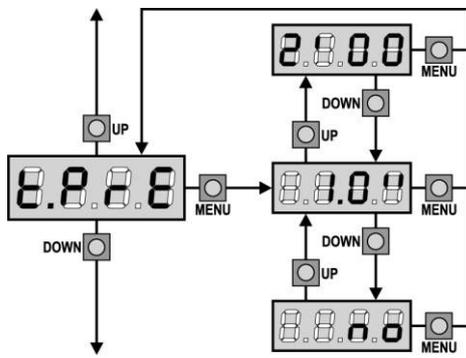
### Backlash time

It could be useful to give a closing command to motors, to help the electric lock release.

The control unit controls the motors in reduced power in closing direction for the setup time.

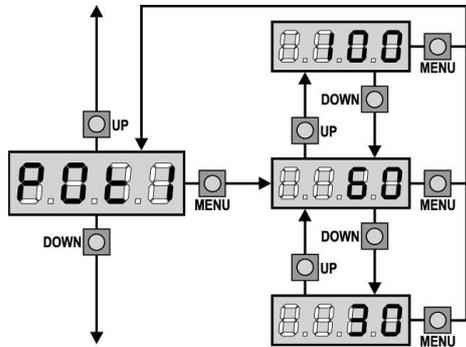
The backlash precedes the electric lock release. It is possible to reverse the order by setting a lock advance time higher than the backlash one.

**!** **WARNING:** in case the gate has no electric lock, set the value 0



### Pre-blinking time

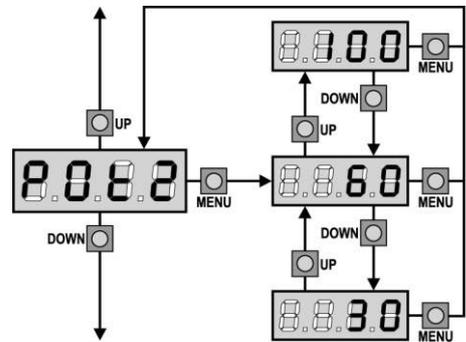
Before any gate movement, blinker will be activated for **t.PrE** time, to warn about the incoming motion.



### Motor 1 power

This menu allows adjusting the motor 1 power. The displayed value is the percentage of max. motor power.

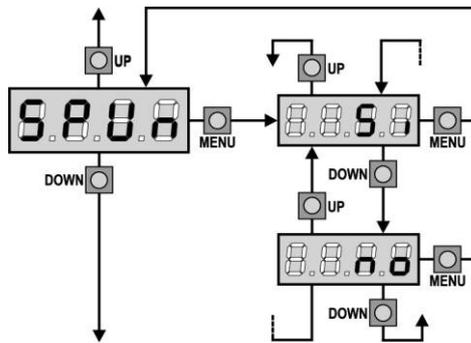
**WARNING:** In case an hydraulic motor is used, set value 100.



### Motor 2 power

This menu allows adjusting the motor 2 power. The displayed value is the percentage of max. motor power.

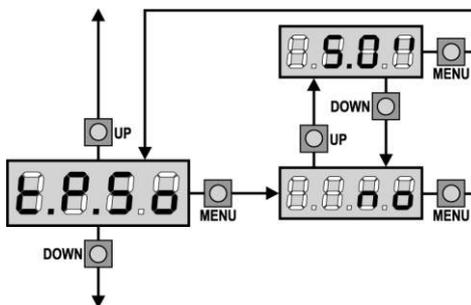
**WARNING:** In case an hydraulic motor is used, set value 100.



### Start off

When the gate is standstill and it begins moving, the initial inertia must be faced, therefore, if your gate is quite heavy, its doors could not move.

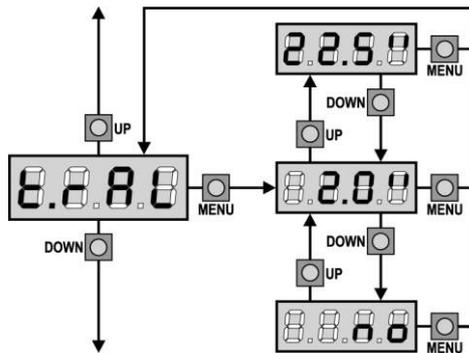
In case the **SPUn** (pickup) function is activated, for the first 2 seconds of motion of each door, the control unit will ignore both **Pot1** and **Pot2** values and it will give motors the maximum power command in order to overcome the gate inertia.



### Soft start (slowed down)

In case this function is enabled, during the first seconds of motion of each door, the control unit will give motors a reduced power command, for a softer start.

**PLEASE NOTE (USE OF HYDRAULIC MOTORS):** This function might NOT work correctly if hydraulic motors are used. In this case, the functions should be disabled in the menu.



### Slowing down time

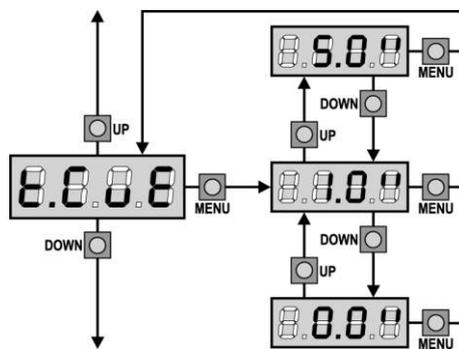
In case this function is enabled, during the last seconds of motion of each door, the control unit will give motors a reduced power command, to avoid a strong impact with the stop end. **t.AP1** is the max. allowed time.

#### WARNING:

- In case the self-learning function of working times is NOT used, we recommend disabling the slowing down function in order to measure both opening and closing times, and to enable it again once the setup has been carried out. The control unit will automatically consider the working time delay caused by the slowing down.
- If partial opening time **t.APP** is shorter than **t.AP1**, there will be no slowing down during the pedestrian cycle opening.

#### **PLEASE NOTE (USE OF HYDRAULIC MOTORS):**

**This function might NOT work correctly if hydraulic motors are used. In this case, the functions should be disabled in the menu.**

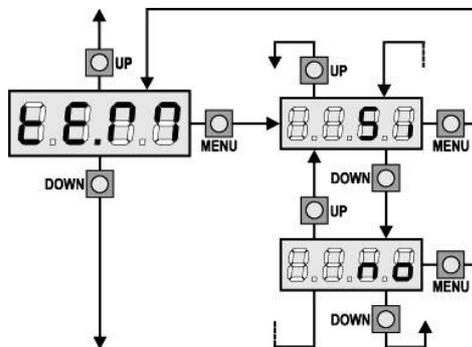


### Fast closing time after slowing down

If a slowing time other than 0 is set up, it could be likely that the gate speed is not enough for the lock to fasten during the closing phase.

In case this function is enabled, once the slowing down phase is finished, the control unit will give a normal speed command (that is to say, with no slowing down) for the set up time, and then it will open the gate for a second fraction, to avoid leaving the motor under stress.

**PLEASE NOTE: Set to 0 if the gate is not fitted with electro-locks or if slowing is disabled.**

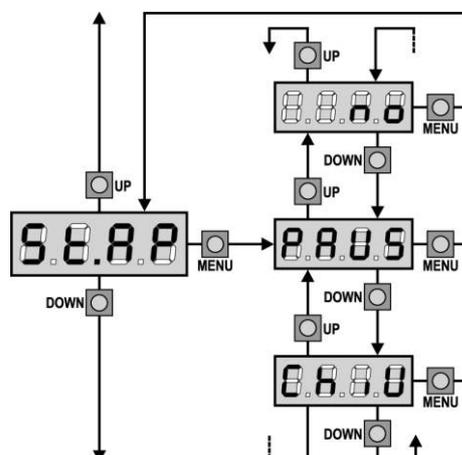


### Enabling the motor test

When the motors are not connected directly to the main terminal board, but controlled by relay or remote switches, the control devices are not sufficiently charged and the motor function test might fail. This menu allows motor control device verification to be enabled or disabled prior to each cycle.

- Si** test enabled
- no** test disabled

**PLEASE NOTE: This test is important for safe use of the gate. GR recommends disabling the test ONLY when the control unit is not connected directly to the motors.**



### Start command during the opening phase

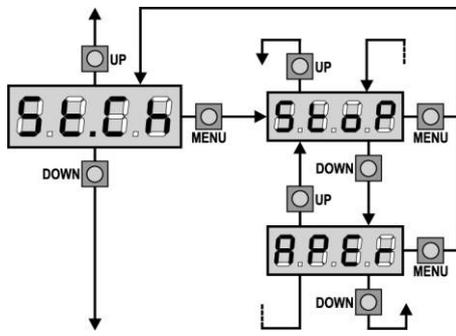
This menu allows fixing the control unit conduct in case it receives a Start command during the opening phase.

- PAUS** The gate stops and goes to pause.
- ChiU** The gate immediately starts closing.

**no** The gate go on with the opening phase (command is ignored).

Select option **PAUS**, to set up the "step-by-step" operation logic.

Select option **'no'**, to set up the 'always open' operation logic.



### Start command during the closing phase

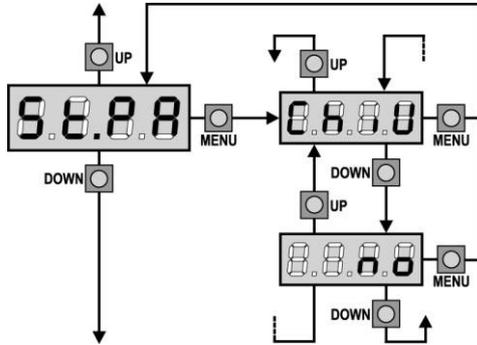
This menu allows fixing the control unit conduct in case it receives a Start command during the closing phase.

**StoP** The gate stops and its cycle is considered as finished.

**APer** The gate opens again.

Select option **StoP**, to set up the "step-by-step" operation logic.

Select option **APer**, to set up the 'always open' operation logic.



### Start command during the pause

This menu allows fixing the control unit conduct in case it receives a Start command when the gate is open during its pause phase.

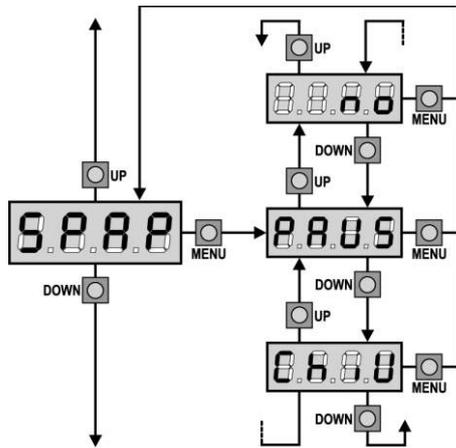
**ChiU** the gate starts closing.

**no** command is ignored.

Select option **ChiU**, to set up the "step-by-step" operation logic.

Select option **'no'**, to set up the 'always open' operation logic.

Apart from selected option, the start command lets the gate close if it has been stopped by a stop command or if the automatic closing was not enabled.



### Pedestrian Start during the partial opening phase

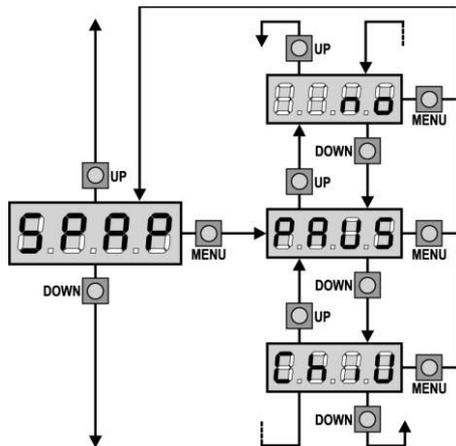
This menu allows fixing the control unit conduct in case it receives a Pedestrian Start command during the partial opening phase.

**PAUS** The gate stops and goes to pause.

**ChiU** the gate immediately starts closing.

**no** the gate goes on with the opening phase (command is ignored).

**! WARNING: a Start command in any phase of partial opening will cause the total opening; the Start Pedestrian command is always ignored during a total opening.**



### Pedestrian Start during the partial opening phase

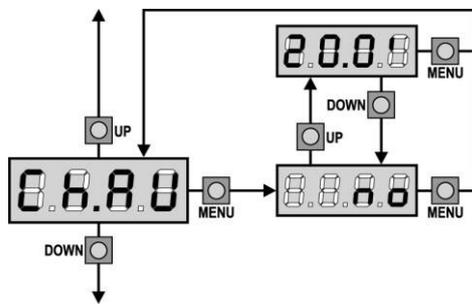
This menu allows fixing the control unit conduct in case it receives a Pedestrian Start command during the partial opening phase.

**PAUS** The gate stops and goes to pause.

**ChiU** the gate immediately starts closing.

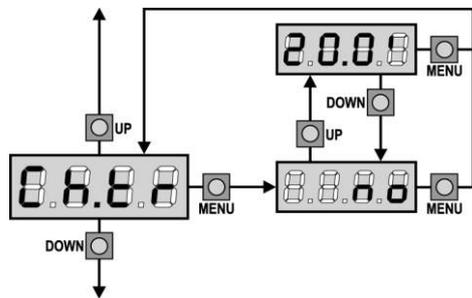
**no** the gate goes on with the opening phase (command is ignored).

**! WARNING: a Start command in any phase of partial opening will cause the total opening; the Start Pedestrian command is always ignored during a total opening.**



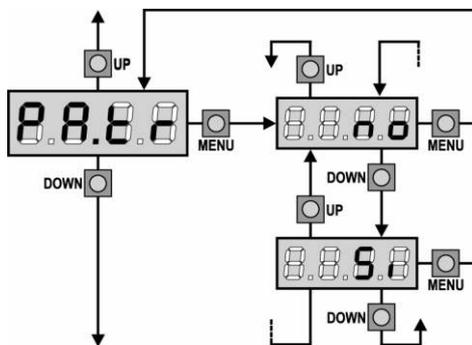
### Automatic closing

During the automatic operation, the control unit will automatically close the gate when a set-up time expires. The Start command, if enabled by **St.PA** menu, allows closing the gate before the set up time expires. In semi-automatic operation, that is to say, if the automatic closing function is disabled by setting the value to zero ('no' will be displayed), the gate can be closed through the start command only: in this case, **St.PA** menu setup will be ignored. If the control unit receives a Stop command when the gate is in pause, it will automatically pass to the semi-automatic operation.



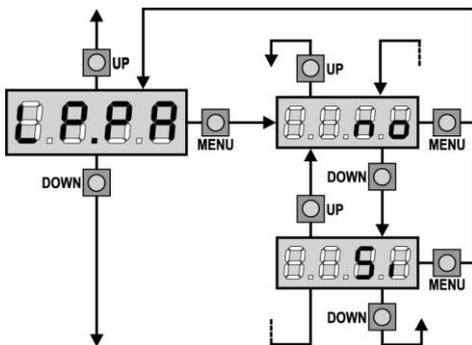
### Closing after transit

During the automatic operation, the pause count down starts from the set up value each time a photocell operates during the pause. If the photocell operates during the opening time, this time will be immediately stored as pause time. This function allows having a fast closing as soon as transit through the gate is completed, therefore, a time shorter than **Ch.AU** is generally used. **Ch.AU** will be used when 'no' is set up. As for semi-automatic operation, this function is not active.



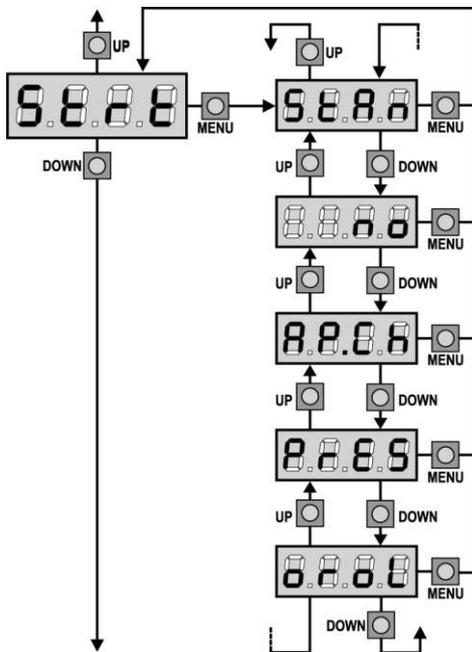
### Pause after transit

In order to let the gate open for the shortest possible time, it is possible to stop the gate once the passage before the photocells is detected. If the automatic working is enabled, the time of the pause is **Ch.tr**. If the photocells are **type 1** and **type 2**, the gate enters the phase of pause only after the detections before both the photocells.



### Blinker during pause time

Blinker usually operates during the gate motion only; however, if this function is enabled, blinker will be on during the pause time too.



### Start input function

This menu allows selecting input operation modes (see paragraph "Activation inputs"):

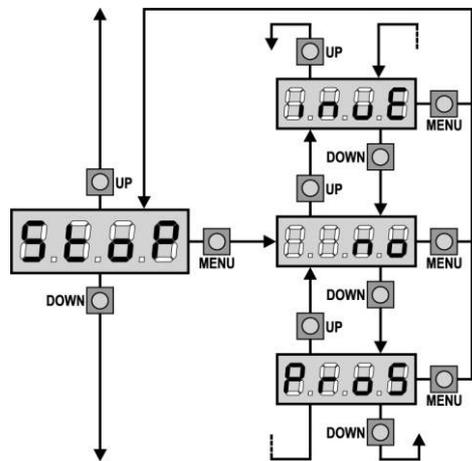
**StAn** Start and Pedestrian Start input standard operation, according to menu setups.

**no** Start inputs from terminal board are disabled. Radio inputs operate in **StAn** mode.

**AP.CH** Start impulse always controls the opening phase, Pedestrian Start always controls the closing phase.

**PrES** Manned operation; the gate will open as long as the Start input stays closed and it will close as long as Pedestrian Start stays closed.

**oroL** Timer-operation; the gate stays open while the Start input or Pedestrian Start input is closed; as soon as the contact opens, the pause count-down will start.



### Stop Input

This menu permits to select the functions associated to the command of STOP.

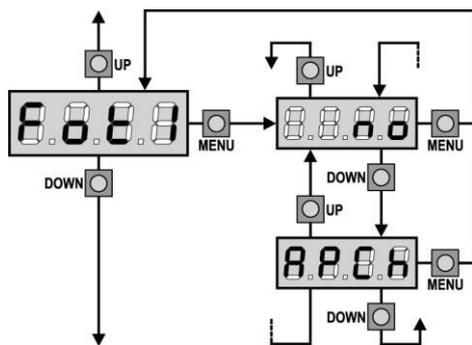
**no** The input STOP is not available.

**ProS** The input STOP stops the gate: pressing the command START the gate continues the motion.

**invE** The command STOP stops the gate: at the next START the gate starts moving in the opposite direction.

The setting of parameter STOP determines also in which direction the gate will move at the next START, if it has stopped because of an intervention of the safety edges or the obstacle sensor. If you set no, the START command restarts the motion in the same direction.

**NOTE:** during the pause, the STOP command will stop the pause time count, the next START command will always close the gate.

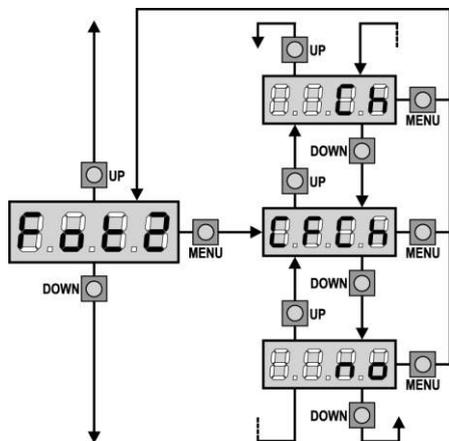


### Photocell 1 input

This menu allows enabling the input for type 1 photocells, that is to say, photocells active both during the opening and closing phase (see paragraph "Installation").

**no** Input disabled (ignored by the control unit). No jumper with the common is required.

**AP.CH** Input enabled.



### Photocell 2 input

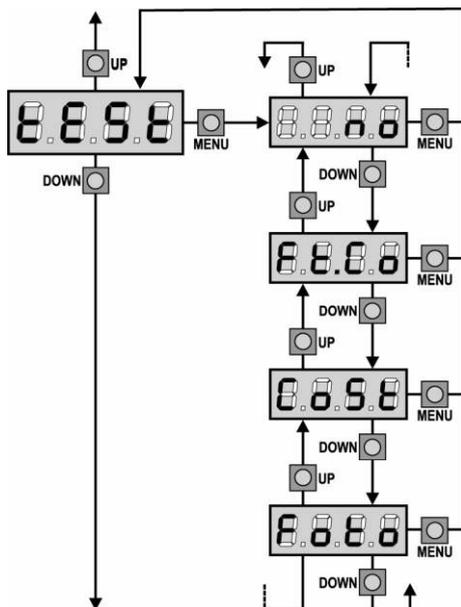
This menu allows enabling the input for type 2 photocells, that is to say, photocells non active during the opening phase (see paragraph "Installation").

**no** Input disabled (ignored by the control unit). No jumper with the common is required.

**CF.CH** Input enabled even at standstill gate too: the opening movement does not start if photocell is interrupted.

**CH** Input enabled for the closing phase only.

**Warning:** if you select this option, you must disable photocell test.



### Test of safety devices

In order to achieve a safer operation for the user, the unit performs a safety devices operational test, before a normal working cycle. If no operational faults are found, the gate starts moving. Otherwise, it will stand still and the flashing light will stay on for 5 sec. The whole test cycle lasts less than one second.

**no** function not active

**Foto** test enabled only for photocells

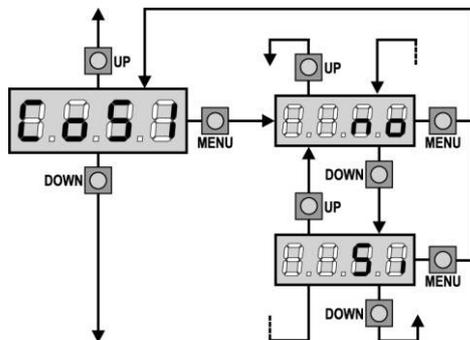
**CoSt** test enabled only for safety edges

**Ft.Co** test enabled either for photocells or for safety edges

**WARNING:** The Test of safety devices should be working in order to grant more safety during installation and programming.

**WARNING:** it is possible to test safety edges only if a control unit specially provided for this function has been installed.

**WARNING:** The devices must be connected as shown in the dedicated section



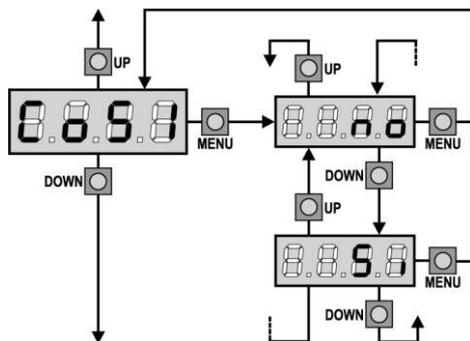
### Safety ribbon 1 input

This menu allows enabling the input for type 1 safety ribbon, that is to say, fixed ribbons (see paragraph "Installation").

**no** Input disabled (ignored by the control unit).

No jumper with the common is required.

**Si** Input enabled.



### Safety ribbon 1 input

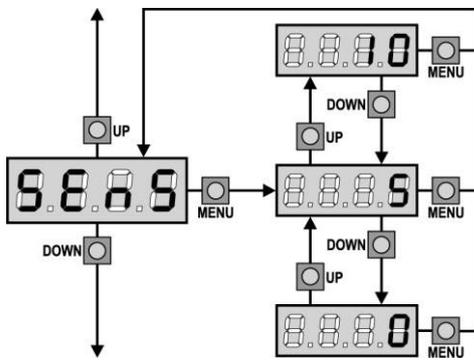
This menu allows enabling the input for type 1 safety ribbon, that is to say, fixed ribbons (see paragraph "Installation").

**no** Input disabled (ignored by the control unit).

No jumper with the common is required.

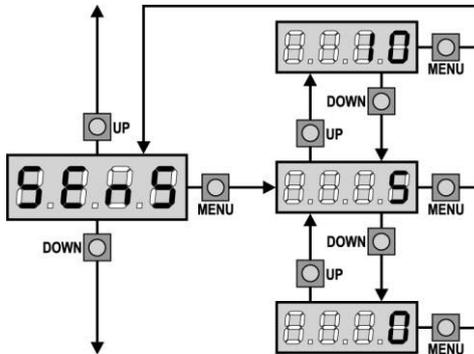
**Si** Input enabled.





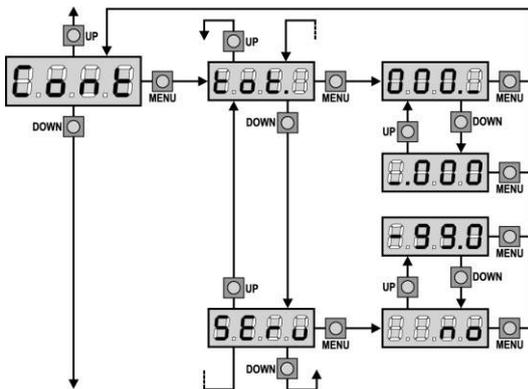
### Obstacle Sensor Enabling

This menu allows the sensitivity adjustment of the obstacle sensor over 10 levels, from 1 to 10. By setting up "0", sensors will be disabled, increasing the value the sensitivity increase. The control unit automatically adjusts the sensor on the most suitable level, according to each motor set up power. In case the safety operation is deemed not to be fast enough, the sensitivity level can be slightly increased. If the gate stops where no obstacles are present, you should reduce the sensitivity level. (See paragraph "Obstacle sensor operation" hereafter).



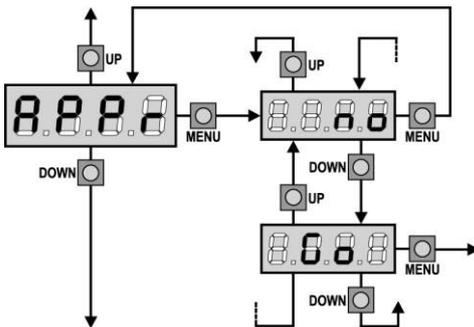
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### Counter viewing

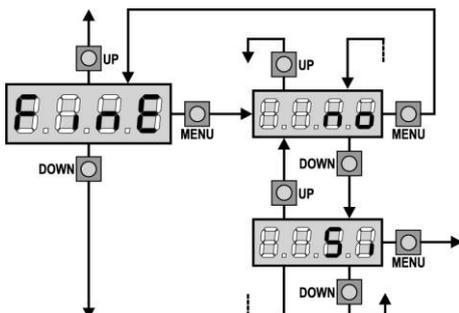
This menu allows viewing the counter of completed opening cycles and it also enables the final user to set up the times of service required (see paragraph "Reading of cycle counter" below).



### Automatic Learning of the Operation Time

This menu will activate a procedure enabling the control unit to automatically find the best duration of the operation time. (See paragraph "Quick Configuration"). When you select **Go**, configuration menu closes and the learning cycle starts.

**⚠ WARNING: The procedure of the operation time automatic learning can be started only if the Start inputs are set up on the STANDARD mode (StAn).**



### End of Programming

This menu allows to finish the programming (both default and personalized) saving the modified data into memory. **no** Further corrections to carry out: do not quit the programming.

**Si** End of programming.

**THE INSERTED DATA HAVE BEEN MEMORIZED: THE CONTROL UNIT IS READY TO BE USED.**



## OPERATION DEFECTS

This paragraph shows some possible operation defects, along with their cause and applicable remedy. **MAINS led does not switch on** It means that there is no voltage on **CITY1** control unit card.

1. Before acting on the control unit, disconnect through the disconnecting switch on the power line and remove the power supply terminal.
2. Be sure that there is no voltage break upstream the control unit.
3. Check whether the fuse is burnt-out, if so replace it with same value.

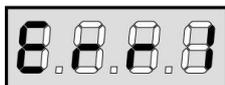
## OVERLOAD led is on

It means that there is an overload on accessory power supply.

1. Remove the extractable part containing terminals 12 to 21. OVERLOAD led will switch off.
2. Remove the overload cause.
3. Reinsert the terminal board extractable part and check that this led is not on again.

## Error 1

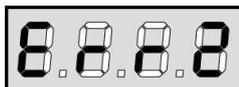
The following writing appears on display when you exit from programming:



It means that changed data could not be stored. This kind of defect has no remedy and the control unit must be sent for repair.

## Error 2

When a Start command is given and the gate does not open and the following writing appears on display:



It means that triac test failed. Before sending the control unit to V2 for repair, be sure that motors have been properly connected. In case motor 2 is not connected, be sure that **t.AP2** menu item is on **0.0**".

## Error 3

When a Start command is given and the gate does not open and the following writing appears on display:

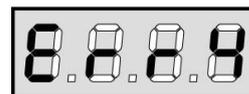


It means that the photocell test failed.

1. Be sure that no obstacle interrupted the photocell beam when the Start command was given.
2. Be sure that photocells, as enabled by their relevant menus, have been installed actually.
3. If you have photocells 2, be sure that **Fot2** menu item is on **CF.CH**.
4. Be sure that photocells are powered and working; when you interrupt their beam, you should hear the relay tripping.

## Error 4

After few centimeters during the opening phase the gate stops and the display shows:



It means that the limit switches in closing phase have not been released. Make sure that the limit switches are correctly connected and the gate, opening, let the limit switch open.

## Error 5

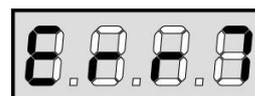
Once given a start control, the gate does not open and the display shows:



It means that the test of the safety edges failed. Make sure that the control unit driving the safety edges is correctly connected and properly working. Make sure that the safety edges enabled by menu are actually installed.

## Error 7

This indicates an error in the encoders' operation.

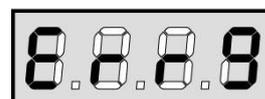


There are three possible causes:

1. With the encoders connected, even if they are not enabled, for a few instants after movement of a gate panel. This means that the connection to the encoder for that gate panel is reversed. Exchange terminal **12** with **13**, or **14** with **15**
2. With the encoders enabled, once a START command is received: This means that the encoders have not been initialized. For the encoders to operate correctly, the self-learning procedure must be performed.
3. With the encoders enabled and initialized, a few seconds after movement begins: This means that an encoder is NOT correctly operating. Encoder malfunction or broken connection.

## Error 9

When you are trying to change the control unit setups and then following writing appears on display:



It means that programming was locked by means of the programming lock key (code **CL1**). It is essential to insert the key into the specific OPTIONS connector and unlock the control unit prior to altering the settings.

## Too long pre-blinking

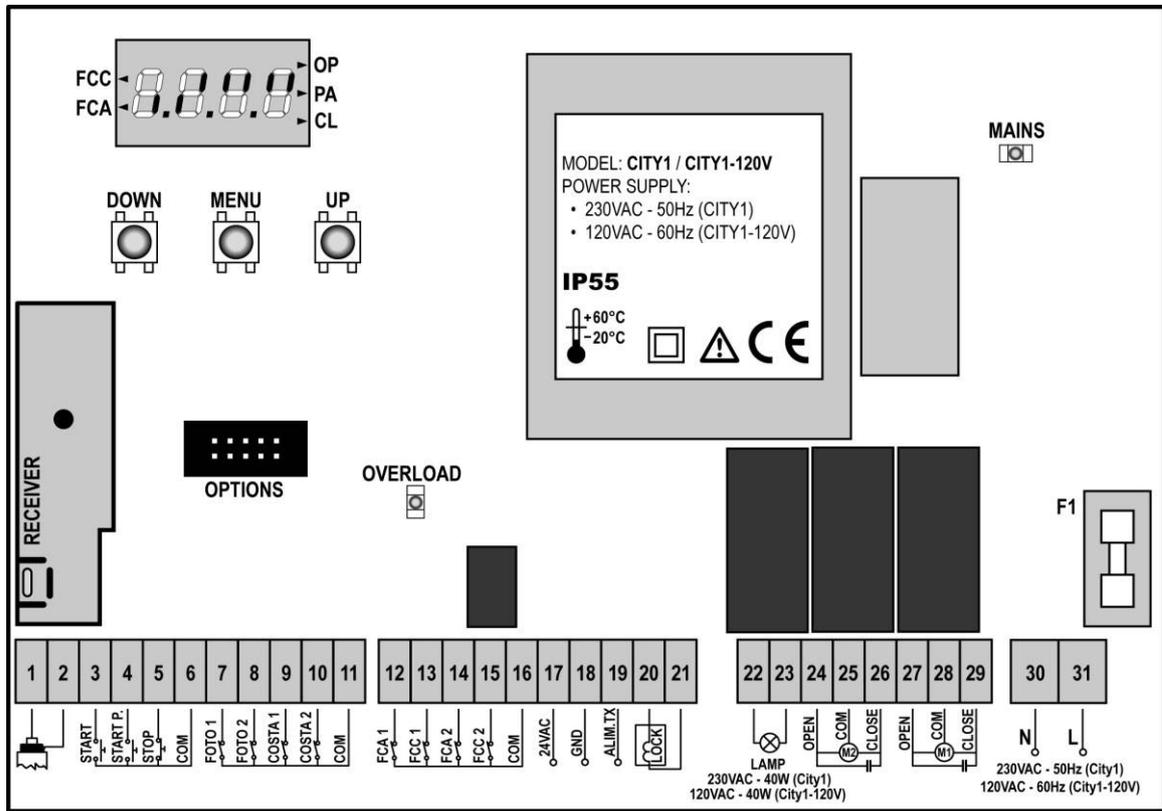
When a Start command is given and the blinker switches on immediately but the gate is late in opening, it means that the setup cycle count -own expired and the control unit shows that service is required.

**CITY1 FUNCTION TABLE**

DISPLAY	DATA	DESCRIPTION	DEFAULT SCor	DEFAULT AntE	MEMO DATA
dEF.	no	It does not load the V2 standard data	no	no	
	SCor	Predefined programming for a typical sliding gate.			
	AntE	Predefined programming for a typical two-door gate			
t.AP1	0.0" ÷ 2.0'	Gate 1 opening time	22.5"	22.5"	
t.AP2	0.0" ÷ 2.0'	Gate 2 opening time	0.0"	22.5"	
t.APP	0.0" ÷ t.AP1	Opening time of pedestrian gate	6.0"	6.0"	
t.Ch1	0.0" ÷ 2.0'	Gate 1 closing time	23.5"	23.5"	
t.Ch2	0.0" ÷ 2.0'	Gate 2 closing time	0.0"	23.5"	
t.ChP	0.0" ÷ t.Ch1	Closing time of pedestrian gate	7.0"	7.0"	
t.C2P	0.5" ÷ 2.0'	Leaf 2 closing time during pedestrian cycle	no	2.0"	
	no	- Function disabled			
r.AP	0.0" ÷ 2.0'	Gate delay during opening	1.0"	1.0"	
r.Ch	0.0" ÷ 2.0'	Gate delay during closing	3.0"	3.0"	
t.SEr	0.5" ÷ 2.0'	Electrical lock operation time	no	2.0"	
	no	- Lock is not energized (it corresponds to 0)			
t.ASE	0.0" ÷ 2.0'	Lock advance time	0.0"	1.0"	
t.inv	0.5" ÷ 3.0"	Backlash time	no	no	
	no	- Backlash disabled (it corresponds to 0)			
t.PrE	0.5" ÷ 2.0'	Pre-flashing time	1.0"	1.0"	
	no	- Pre-flashing disabled (it corresponds to 0)			
Pot1	30 ÷ 100%	Motor 1 power	60	60	
Pot2	30 ÷ 100%	Motor 2 power	-	60	
SPUn	no/Si	Start off	no	Si	
t.PSo	0.5" ÷ 3.0"	Slowed down starting time	1.5"	no	
	no	- Slowed down starting disabled			
t.raL	0.5" ÷ 22.5"	Slow down time	2.0"	2.0"	
	no	- Slow down disabled			
t.CVE	0.0" ÷ 3.0"	Fast closing time after slowing down during closing	0.0"	1.0"	
tE.M	Si/no	Enabling the motor test	Si	Si	
St.AP		Start in opening	PAUS	PAUS	
	no	- Start command is not available			
	ChiU	- Command close gate			
	PAUS	- Stop the gate and goes in pause			
St.Ch		Start in closing	StoP	StoP	
	Stop	- Start command stop the gate			
	APEr	- Start command open the gate			
St.PA		Start in pause	ChiU	ChiU	
	no	- Start command is not available			
	ChiU	- Start command closes the gate			
SPAP		Pedestrian in opening	PAUS	PAUS	
	no	- Pedestrian start command is not available			
	ChiU	- Pedestrian start command closes the gate			
	PAUS	- Gate goes in pause			
Ch.AU		Automatic closing	no	no	
	no	- The automatic closing is not active (it corresponds to 0)			
	0.5" ÷ 20.0'	- The gate closes after the setup time			

DISPLAY	DATA	DESCRIPTION	DEFAULT SCor	DEFAULT AntE	MEMO DATA
Ch.tr		Closing after passage	no	no	
	no	- Closing after passage disabled			
	0.5" ÷ 20.0'	- Gate stop for a time to be set between 0.5" to 20'			
PA.tr	no/Si	Pause after transit	no	no	
LP.PA	no/Si	Flashlight in pause	no	no	
St.rt		Operation modes	StAn	StAn	
	no	- Start inputs from terminal board are disabled			
	StAn	- Standard operation			
	AP.CH	- Separated opening and closing commands			
	PrES	- Manned operation			
	oroL	- Timer operation			
StoP		STOP input	no	no	
	no	- STOP input not available			
	invE	- STOP command stops the gate: START command starts moving in the opposite direction			
	ProS	- STOP command stops the gate: pressing the START command gate continues the motion			
Fot 1		PHOTO 1 input	APCh	no	
	APCh	- Input is available for the connection of the photocell			
	no	- Not available			
Fot 2		PHOTO 2 input	CFCh	CFCh	
	CFCh	- Photocell is active in closing and also when the gate is still			
	no	- Not available			
	Ch	- Photocell is active during the closing			
tESt		Test of safety devices	no	no	
	no	- Function not active			
	Foto	- Test enabled only for photocells			
	CoSt	- Test enabled only for safety edges			
	Ft.Co	- Test enabled either for photocells or for safety edges			
CoS1	no/Si	Border 1 input (fixed border)	no	no	
CoS2	no/Si	Border 2 input (mobile border)	no	no	
FC.En	no/Si	End of stroke inputs	Si	no	
riLA	Si/no	Motor Release on Mechanical Stop	Si	Si	
t.inA	0 ÷ 8	Max. gate quiescent time	0	0	
ASM	0.5" ÷ 3.0"	Anti-skid	0.5"	0.5"	
	no	- Function disabled			
SEnS	0 ÷ 10	Obstacle sensor level	5	5	
Cont		Counter viewing	tot	tot	
	tot.	- Total number of completed cycles (views in thousands or in units)			
	Man	- Number of cycles before the next request for service (such a number has been rounded off to hundreds and it can be set up on 1000-step; in case it is set up on 0, the request will be disabled and no will be viewed)			
APPr		Automatic learning of the operation time	no	no	
	no	- Function disabled			
	Go	- Start up of the automatic learning procedure			
FinE		End of programming	no	no	
	no	- It does not exit from the program menu			
	Si	- It exits from the program menu by storing the setup parameters			

## ELECTRIC CONNECTIONS TABLE



1	Antenna
2	Antenna shield
3	Opening control for the connection of control devices with N.O. contact
4	Opening controls for pedestrian access for the connection of control devices with N.O. contact
5	Stop command. N.C. contact
6	Common (-)
7	Photocells type 1. N.C. contact
8	Photocells type 2. N.C. contact
9	Safety ribbons type 1 (fixed). N.C. contact
10	Safety ribbons type 2 (mobile). N.C. contact
11	Common (-)
12	End of stroke in door 1 opening phase. N.C. contact
13	End of stroke in door 1 closing phase. N.C. contact
14	End of stroke in door 2 opening phase. N.C. contact
15	End of stroke in door 2 closing phase. N.C. contact
16	Common (-)
17 - 18	Power output 24 VAC for photocells and other accessories
18 - 19	Photocell TX power supply for functional test.

20 - 21	Electric lock 12VAC
22 - 23	Flashing light 230VAC 40W (CITY1) 120VAC 40W (CITY1-120V)
24	Motor 2 opening
25	Motor 2 common
26	Motor 2 closing
27	Motor 1 opening
28	Motor 1 common
29	Motor 1 closing
30	Neutral 230 VAC / 120 VAC
31	Power phase 230 VAC / 120 VAC
F1	5A (CITY1) / 8A (CITY1-120V)
OPTIONS	Optional modules connector
MAINS	It shows that the control unit is power supplied
OVERLOAD	It shows that there is an overload on accessories power supply
FCC	It shows the opening end of stroke activation
FCA	It shows the closing end of stroke activation
OP	Opening in progress
PA	Pause (gate opened)
CL	Closing in progress

## MAINTENANCE

The barrier must be maintained in order to conserve conditions which guarantee safety and correct operation.



***Before proceeding with maintenance, ensure that the barrier is safe, switching off the ON/OFF switch on the electrical panel and locking the electrical panel itself. Also remember that a preload spring is installed inside the automatism and great care must be taken when adjusting it.***

***Always use original spare parts. Do not perform adjustments which modify the barrier or alter the calibrations.***

## RESIDUAL RISKS

- If there is no coordination between the residual current device and the earthing system, for places at greater electrical risk, the user is exposed to the risk of an electric shock in the event of a fault.
- If the assembly area is poorly lit, the user is exposed to the risks or accidental knocks and injuries;
- If the return spring or the ascent/descent speed is not correctly calibrated, the user is exposed to the risk of traumas caused by knocks from the barrier.

## REGULAR MAINTENANCE INTERVENTIONS

Operation	Frequency	Person responsible	Method
Check that the protection devices are in working order	Daily	Operator	Check that the stops are efficient, the guards are in position and the signs are intact.
Check the positions of the end runs	As required	User	Disconnect power and proceed as described in the manual.
Check the descent/ascent force of the barrier	Every six months	User/maintenance technician	Disconnect power; check that the maximum force generated to stop the barrier during movement is less than 150N. If the value measured is greater, adjust the preload spring.
Check the protection against indirect contacts	Every six months	Electrical maintenance technician	Check the intervention times of the residual current switch and check that the protection circuit (PE) is earthed correctly.

## TROUBLESHOOTING

There follows a list of some causes and possible solutions for a series of faults which could occur and lead to incorrect or non-operation of the moveable barrier.

Faults	Possible cause	Solution
The barrier does not perform the open/close commands	No electrical power	Check for the presence of electrical energy.
	The ON/OFF switch is OFF or has been triggered due to a fault	Check the conditions of the switch and turn ON again if necessary
	The photocells are not in the light or a foreign element is present	Check the photocells
	Opening of the automation-barrier connection through the emergency manoeuvre	Close the connection using the designated key
	The end run is not closed	Check the action and the continuity of the end run contacts
The barrier goes up and then remains blocked in that position	The spring is too taut and the automatism cannot overcome the weight of the barrier and the return action of the spring	Adjust spring calibration
	The arm used is too long or too heavy	Adjust spring calibration
When the barrier comes down, it hits the fixed support at the end	Mechanical end run not positioned correctly, spring not preloaded enough	Adjust the calibration of the end run and the spring preload

**AUTOMATIC SOLUTIONS AUSTRALIA PTY LTD**  
**PO BOX 1034 CANNING VALE WESTERN AUSTRALIA 6970**  
**TECHNICAL HELP – [service@automaticsolutions.com.au](mailto:service@automaticsolutions.com.au)**

# SELF INSTALL - NEED TECHNICAL ASSISTANCE?

## OPTION 1: DIRECT WITH THE SERVICE DESK – QUICKEST AND MOST EFFECTIVE METHOD

Submit your enquiry direct with the service desk at – [service@automaticsolutions.com.au](mailto:service@automaticsolutions.com.au)

The service desk has the most experienced staff in Australia to help with your problem but they need your help.

- Describe your problem in detail and as clearly as possible. Don't forget to include a telephone number.
- Be certain to detail which model or models of you are working with.
- Send photos of the installation – they love photos. The people at the service desk are good but they are even better when they can see the installation. Send photos of the overall scene so they can see the entire installation. Also send photos of the wiring to the control board and any other part of the installation you think is relevant.
- Send video if appropriate. Smartphone's these days take remarkably good video in small file sizes which can be emailed in a moment. If your problem needs a video to show the issue please feel free to send it.

**NOTE: THIS IS BY FAR THE FASTEST AND MOST SUCCESSFUL WAY TO SOLVE YOUR PROBLEM  
PHOTOS AND VIDEOS ARE THE NEXT BEST THING TO BEING THERE**

## OPTION 2: LODGE YOUR ENQUIRY LOCALLY - SLOWER BUT CAN STILL BE EFFECTIVE

Make contact with the store of purchase. Branch staffs are typically not technicians and dependent on their length of service will have varying degrees of technical knowledge. If they cannot help however they will certainly either source help locally from their technicians or make contact with the service technicians on your behalf.

## OPTION 3: SERVICE CALL WITH AUTOMATIC SOLUTIONS TECHNICIAN – SLOWEST METHOD

If you fall within the local branch service area it may be possible to book a local technician to look at your installation. Wait times will vary dependent on local workloads. The cost is a service fee which includes the first half hour and the hourly rate thereafter. If any Automatic Solutions provided parts are found to be defective and within warranty these will be provided free of charge.

(NOTE: If you suspect that any parts are defective and within warranty you may wish to consider option 4)

*A note on this option: If you decide on this option you will be asked to sign an "authorisation to proceed" which will provide legal authority and payment security. This form has three options available of which only the first two are available to you. The third option is for warranty repairs only for full install customers. Self install customers requiring warranty only service need to refer to option four below.*

**IMPORTANT: IN SHORT THIS OPTION WILL INCUR CHARGES**

## OPTION 4: RETURN THE PRODUCT IF BELIEVED TO BE FAULTY

As a self install customer who has purchased product if you believe the product to be faulty rather than an installation or site problem you have the option of returning the product for evaluation and to exercise your right to a replacement, repair or refund as applicable. All returned product is forwarded immediately to the service technicians for evaluation and response. There are two main methods available to return product –

- Direct to the service centre – this is the quickest method as it cuts out the branch delay
- Via the branch of purchase – slower because of the delay at the branch

When choosing this option you need to complete a product return form. This form gives you all the information on procedure involved and where to send to. These are available at the branch of purchase, can be emailed to you (contact your branch), or available here - <http://automaticsolutions.com.au/page/warranty.php>